

Liquid-Solid transition : BCC lattice is the most stable one

As an example, we shall describe how to describe the liquid-solid transition using the Landau theory. In the Landau theory,

the order parameters are  $n_G$  defined by

$$\langle f_n(x) \rangle = \langle n(x) \rangle - n_0 = \sum_G n_G e^{i\vec{G} \cdot \vec{x}}$$

$n_G \neq 0$  for crystals.

There are infinite many  $G$ 's, thus infinite many  $n_G$ 's.

Near the transition, we can expand the

$$\text{free energy } \frac{F(D, T, n(n))}{V} = f_0 + f_1 + f_2 + f_3 + \dots \quad (1)$$

where  $f_0$  = Free energy of liquid

and  $f_n (n \geq 1)$  contains terms with  $n_1, n_2, n_3, \dots, n_n$

$$\text{with } G_1 + G_2 + G_3 + \dots + G_n = 0 \quad (2)$$

So that  $f_n$  is invariant under  $\vec{r} \rightarrow \vec{r} + \vec{R}$ :

$$n_{G_1} \dots n_{G_n} \rightarrow n_{G_1} n_{G_2} \dots n_{G_n} e^{i(G_1 + G_2 + \dots + G_n) \cdot \vec{R}} = n_{G_1} \dots n_{G_n}$$

Clearly, for  $n=1$ , ② implies  $G=0$

$$\therefore f_1 = 0$$

$$n=2, \quad G_1 = -G_2 \quad \therefore \quad f_2 = \sum_G A_G |nG|^2$$

$$(nG = nG^*)$$

$$n=3, \quad f_3 = \sum_{G_1, G_2, G_3} B_{G_1, G_2, G_3} n_{G_1} n_{G_2} n_{G_3}$$

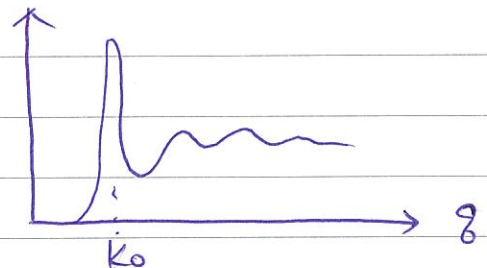
$$n=4, \quad f_4 = \sum_{\substack{G_1, G_2 \\ G_3, G_4}} C_{G_1, G_2, G_3, G_4} n_{G_1} n_{G_2} n_{G_3} n_{G_4}$$

...

The problem seems to intractable.

However, if we approach the crystal from the liquid side, as indicated by the

structure factor,



it would be reasonable

to assume <sup>that</sup> only one length scale, i.e., one wave length for the density wave arises.

(Alexander & McTigue, Phys. Rev. Lett. 41, 702, 1978)

Therefore, we shall focus on  $\vec{G}_i$  with the

same magnitude  $G$  around  $K_0$ . The isotropy of

liquid implies different directions of  $\vec{G}$  are

equivalent. Hence all  $A_G, B_G, G_2, G_3$  &

$G_1, G_2, G_3, G_4$  are the same!

$\therefore$  we shall write  $f_2 = r \sum_G |\vec{G}|^2$

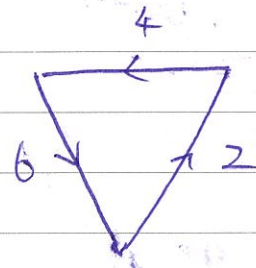
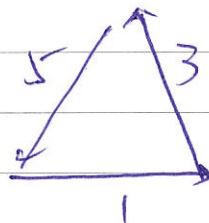
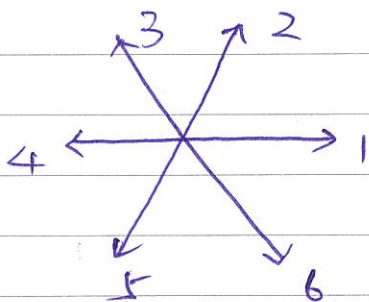
For  $n=3$ , since  $|\vec{G}_i| = G$ ,  $G_1, G_2$ , &  $G_3$  must

form an equilateral triangle. There are

3 possibilities if one collects all possible

equilateral triangles:

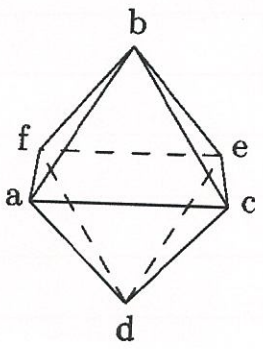
(i) Six  $\vec{G}_i$  ( $i=1,2,3,4,5,6$ ), # of  $\vec{G}_i \equiv m=6$



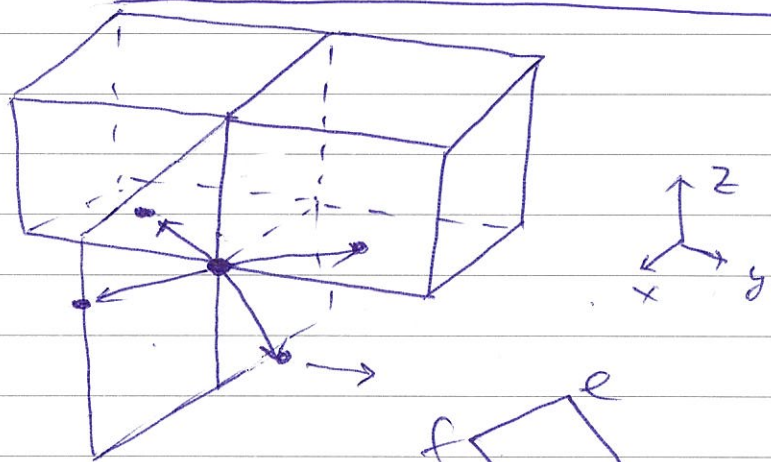
$\Rightarrow$  crystals are hexagonal lattice

(ii) twelve  $\vec{G}_i$ ,  $m=12$  and they are

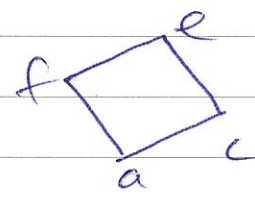
edge vectors of an octahedron.



It's easy to see that  
 acef, abed & fbc d are  
 3 squares of a FCC crystal's  
 nearest neighbouring vectors :  
⇒ crystals are BCC lattices!



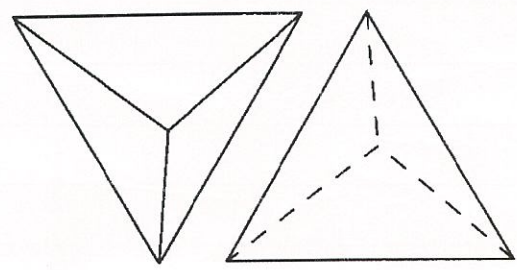
xy plane 4 neighbours  
 yz " " "  
 zx " " "



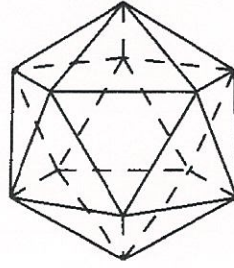
It's also possible to rearrange the octahedron  
 into two tetrahedrons :

$\left\{ \begin{array}{l} \Delta abc, \text{ move } \bar{ce} \text{ to } b, \bar{dc} \text{ to } a, \bar{ad} \text{ to } c \\ \Delta dfe, \text{ move } \bar{af} \text{ to } d, \bar{be} \text{ to } f, \bar{fb} \text{ to } e \end{array} \right.$

$(d \rightarrow a) \quad (d \rightarrow c)$   
 $(b \rightarrow f) \quad (b \rightarrow e)$



(iii)  $m=30$ , they are edge vectors of  
an icosahedron.



For (iii), a solid with a reciprocal lattice generated by the edge vectors of an icosahedron is an icosahedral quasi-crystal!

Depending on sets of  $G_i$ , we have different  $m$ .

For a given  $m$ , since each pair  $G, -G$  is equivalent, we find

$$\begin{aligned} f_2 &= \frac{1}{2} r m |hG|^2 \\ &= \frac{1}{2} r |hG|^2 \quad \text{--- (3)} \\ &\quad \uparrow \\ &\quad \text{rescale } hG \text{ by } \frac{hG}{\sqrt{m}} \end{aligned}$$

For  $n=3$ , one needs to count # of equilateral triangles.

Let  $p$  be the # of triangles that a given  $G_i$  belongs to.

∴  $G_1$  has  $m$  choices, there are  $P$  triangles including  $G_1$ ,  $G_2$  has two choices in each triangle, after  $\vec{G}_1$  &  $\vec{G}_2$  are chosen,  $\vec{G}_3$  is fixed!

∴  $f_3$  can be written as

$$f_3 = \omega \cdot m \cdot z p |nG|^3 e^{i(\theta_1 + \theta_2 + \theta_3)}$$

→ min at  $\theta_1 + \theta_2 + \theta_3 = \pi$

rescale  $|nG| \rightarrow \frac{nG}{\sqrt{m}}$

$$f_3 = - \frac{zwp}{\sqrt{m}} |nG|^3 \quad \omega = \text{a positive coefficient}$$

L --- (4)

To have a lower bound for  $F_U$ , one needs to include  $f_4$ . (otherwise  $f_3$  can be arbitrarily negative).

There are two possible ways for summation

- of 4 vectors,  $\vec{G}_1, \vec{G}_2, \vec{G}_3$  &  $\vec{G}_4$  to zero
- (i)  $\vec{G}_1, \vec{G}_2, \vec{G}_3$  &  $\vec{G}_4$  in the same plane (e.g. two sets of opposite  $G_i$  acf diamond)
  - (ii) non-planar diamond (each vector belongs to 2 non-planar diamonds) (e.g. badc)

$(C_2^4)$ 

For (i), we have 6 ways to pair  $n_{G_1}, n_{G_2}, n_{G_3}, n_{G_3}$

into  $n_G n_G n_{G'} n_{G'}$ .  $\therefore G, G'$  have  $m$  choices

This contributes  $6 \mu m^2 (n_{G'})^2$  ( $n_{G_1}^2, n_{G_2}^2$  are equivalent)

$$\rightarrow 6 \mu |n_G|^4$$

rescale

$$n_G \rightarrow n_G / \sqrt{m}$$

 $\mu = \text{some positive constant}$ 

For (ii),  $m$  choices for  $\vec{G}_1$ ,  $\therefore$  there are

8 non-planar diamonds,  $\vec{G}_1$  belongs to, and there are 3 choices of  $\vec{G}_2$

for a given diamond.

$\therefore$  38 choices for  $\vec{G}_2$

2 choices for  $\vec{G}_3$

1 " for  $\vec{G}_4$

$$\therefore m \times 68 \times \mu |n_G|^4 \xrightarrow{\text{rescale}} \frac{68\mu}{m} |n_G|^4$$

$$\therefore f_4 = 6\mu \left(1 + \frac{8}{m}\right) |n_G|^4 \dots \textcircled{5}$$

$$f = \frac{1}{2} r |n_G|^2 - \frac{zWP}{\sqrt{m}} |n_G|^3 + 6\mu \left(1 + \frac{8}{m}\right) |n_G|^4 \dots \textcircled{6}$$

with  $m=6, P=1, 8=0$ , for hexagonal lattice

$m=12, P=2, 8=4$ , for BCC

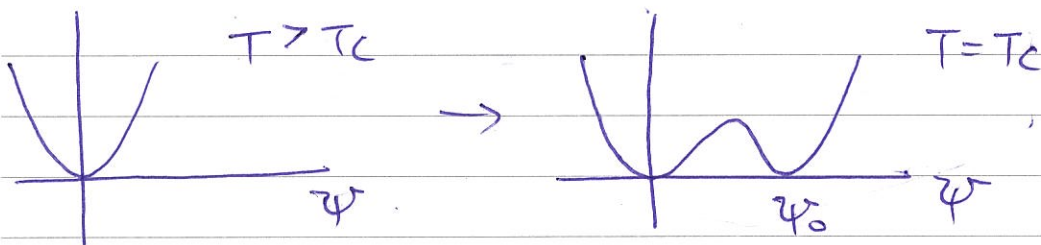
$m=30, P=2, 8=4$ , for icosahedral

quasi crystal 

Now,  $r = \alpha (T - T_c^0)$ . We can find

transition temperature  $T_c$  by requiring

$$\begin{cases} \frac{df}{d\psi} = 0 \\ f(\psi=0, T_c) = f(\psi=\psi_0 \neq 0, T_c) \quad \psi \in [0, 1] \end{cases}$$



$$r\psi - \frac{6WP}{\sqrt{m}} \psi^2 + 24u(1 + \frac{8}{m}) \psi^3 = 0$$

$$\psi = 0 \quad \text{or} \quad r - \frac{6WP}{\sqrt{m}} \psi_0 + 24u(1 + \frac{8}{m}) \psi_0^2 = 0$$

① - ②

$$f(\psi=0, T_c) = 0$$

$$= f(\psi_0, T_c) = -\frac{1}{2} \psi_0^2 \left[ \alpha (T_c - T_c^0) - \frac{2WP}{\sqrt{m}} \psi_0 + 6u(1 + \frac{8}{m}) \psi_0^2 \right]$$

$$\therefore r - \frac{2WP}{\sqrt{m}} \psi_0 + 6u(1 + \frac{8}{m}) \psi_0^2 = 0 \quad \text{--- ②}$$

$$\text{②} - \text{①} \Rightarrow \psi_0 \left[ 18u(1 + \frac{8}{m}) \psi_0 - \frac{4WP}{\sqrt{m}} \right] = 0$$

$$\therefore \psi_0(T_c) = \frac{4WP}{\sqrt{m} \cdot 18u(1 + \frac{8}{m})}$$

Substituting it into eq. ②, we find

$$\alpha (T_c - T_c^0) = \frac{1}{2} \frac{(2WP)^2}{6u(m+8)} = \frac{W^2}{18u} \text{ (hexagonal)} \\ \frac{W^2}{12u} \text{ (BCC)}, \frac{2W^2}{54u} \text{ (Quasi-crystal)}$$



It's clear that BCC crystal has highest  $T_c$ . Therefore, this analysis implies BCC lattice is the most stable one.

Indeed, a large # of materials crystallize from the melt into BCC (may assume some other structures in low temperatures)

In fact, 40 elements have high temperature BCC structures.

Of course, the above analysis does not explain why there are other high temperature structures.

To improve the theory, one needs to introduce a second  $|\vec{G}'| \neq |\vec{G}|$  so that

$$\Delta f = \frac{f}{2} v_{G'} |\vec{h}_{G'}|^2 - v |\vec{h}_G|^2 |\vec{h}_G|. \text{ Clearly,}$$

$$\text{it leads to } |\vec{h}_{G'}| = \frac{v}{v_{G'}} |\vec{h}_G|^2$$

so that  $\Delta f = -\frac{v^2}{2v_{G'}} |\vec{h}_G|^4 < 0$ . This would be the reason why other structures can be

also stabilized. That would require more

complicated analysis!

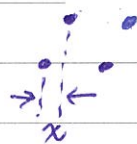
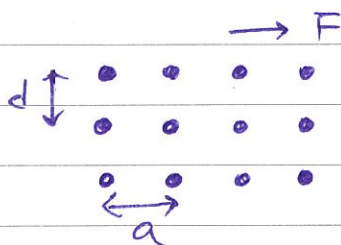
## Defects and 2D melting

One can view the liquid-solid transition from the solid side. In this case, one sees that crystals become more & more deformed with defect proliferation and eventually melt.

Defects play an important role in the mechanical properties of a <sup>real</sup> crystal.

Why are real crystals much weaker than we thought?

Suppose we deform the crystal as follows:



$$\frac{x}{d} \sim \theta \quad (\sin \theta)$$

$u$  (elastic energy per unit volume)

$$= \frac{1}{2} G \left( \frac{x}{d} \right)^2 \quad G = \text{shear modulus}$$

This is valid only for small  $x \ll 1$ .

Experimentally, one can measure  $G$  in the regime  $x \ll 1$  and find  $G \sim 10^{11} - 10^{12} \text{ dynes/cm}^2$

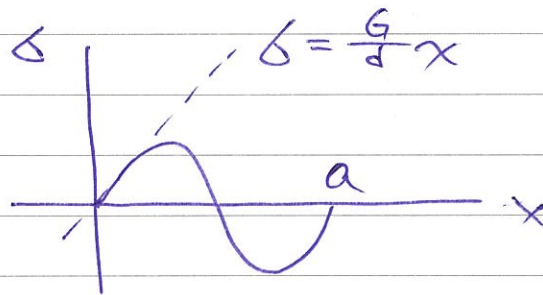
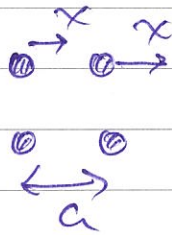
Now, we can extend the above to large

$x$  by noting that the stress  $\sigma = G \frac{x}{d}$   
 $\underbrace{\hspace{1.5cm}}_{\text{Strain}}$

for ideal crystals,

since  $\sigma$  should be periodic in  $x$

with period  $a$  (see the figure on below),



We can approximate  $\sigma$  by

$$\sigma = \frac{G}{d} \frac{a}{2\pi} \sin \frac{2\pi x}{a}$$

$\max \sigma \equiv \sigma_c$  (critical shear stress)

$$\approx \frac{G}{d} \frac{a}{2\pi}$$

if  $d \approx a$ ,  $\sigma \sim \frac{G}{2\pi} \sim 10^{11} \text{ dynes/cm}^2$

If we apply  $\sigma > \sigma_c$ , crystals undergo "slip", i.e. sticking one plane over the other!

From this, one can measure  $\sigma_c$  (expt.)

One finds  $\text{Ag}: \sigma_c = 6 \times 10^6 \text{ dynes/cm}^2$

$\text{Al}: \sigma_c = 4 \times 10^6$  "

Which are  $10^4$  smaller than one expects!

Therefore, real crystals are much weaker than we thought!

Why?

To explain the low yield stress, G.I. Taylor,

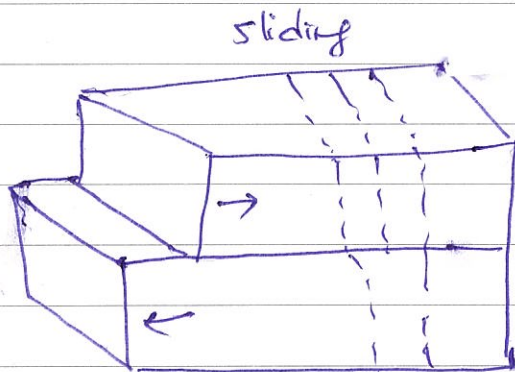
Orowan & Polanyi proposed that slip

propagates by the motion of dislocations,

which were introduced earlier by Prandtl and

Dehlinger. The dislocations proposed are

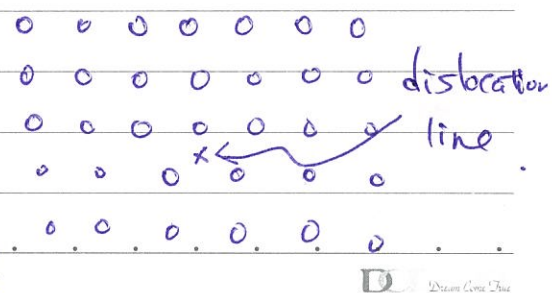
edge dislocations:



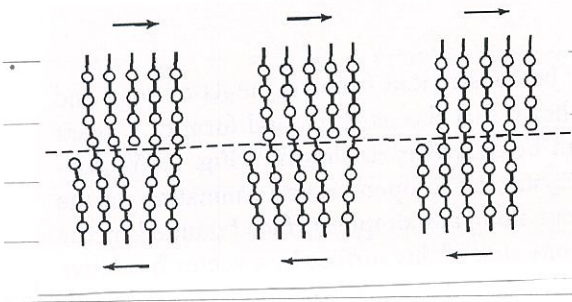
It's equivalent to

insert a half plane

of atoms



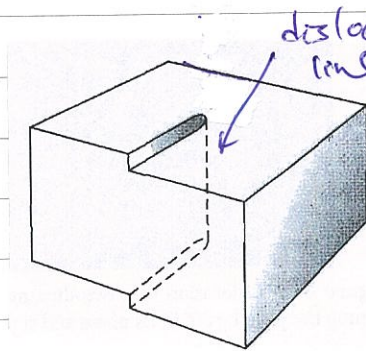
notation:  $\perp$  ← extra plane  
 ← slip plane ( $\parallel \vec{x}_s$ )



One can see that if there are edge dislocations, it's much easier to push/slide the crystal along x directions (see the left figure).

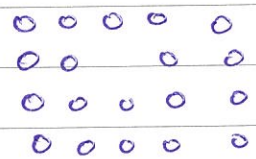
In addition to edge dislocations, there are also other possible defects.

Screw dislocations

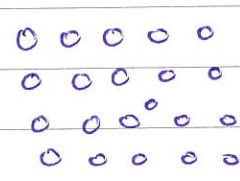


edge & screw dislocations are line defects.

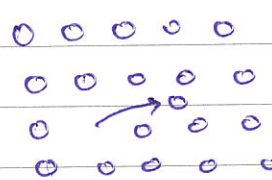
Point defects : Vacancies, interstitials



Vacancy (Schottky defect)



interstitials



Frenkel defect

activation energy to remove one

$n = \# \text{ of point defects (Schottky)}$        $\frac{n}{N-n} = e^{-\frac{E_v}{k_B T}}$  one atom

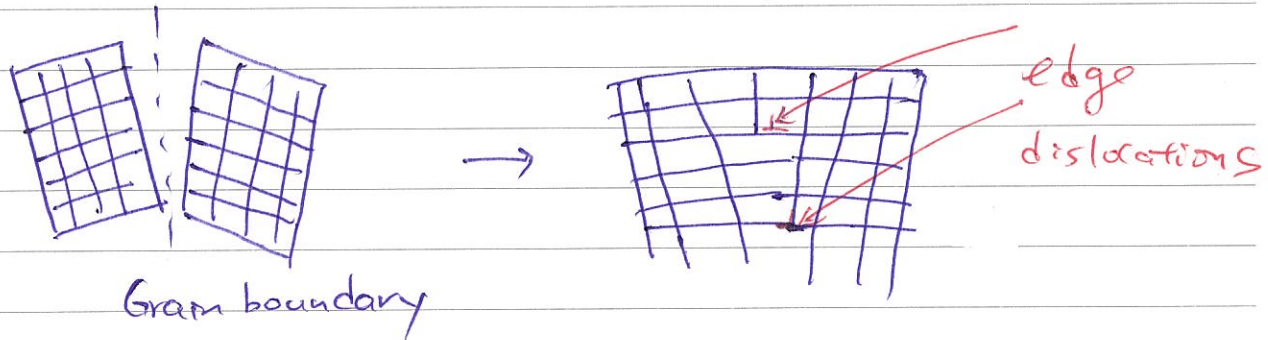
if  $n \ll N$        $\frac{n}{N} \sim e^{-\frac{E_v}{k_B T}}$

$E_v \sim 1 \text{ eV}$        $T \sim 1000 \text{ K}$        $\frac{n}{N} \sim 10^{-5}$

## Surface defects

Grain boundary (low angle)

Can be viewed as a sequence of edge dislocations.



Stacking fault:

ABC ABC AB ABC ABC ABC --  
 ↑  
 stacking fault

twin boundary: (hcp, fcc)

(High  $T_c$  materials such as YBCO have a lot!)

ABCABCABC BAC BAC BA  
 ↓  
 ← · →  
 mirror  
 image

in hcp, A, B, C differ by in-plane positions.

∴ one can slip  $A \rightarrow B$ ,  $B \rightarrow A$

By slipping planes, one can create a twin

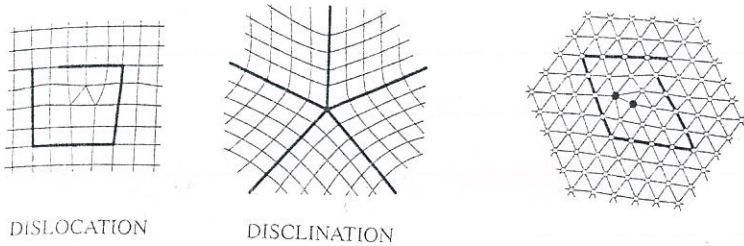
boundary: ABC ABC ABC ABC BAC BAC  
 ↓ ↓  
 BA

## Defects-mediated melting

As we have seen, dislocations are the most important defects to explain the mechanical properties of real crystals.

In addition to dislocations, there are also disclinations which are defects in orientation!

(see left figures)



It is known that two disclinations bounded are equivalent to a dislocation!

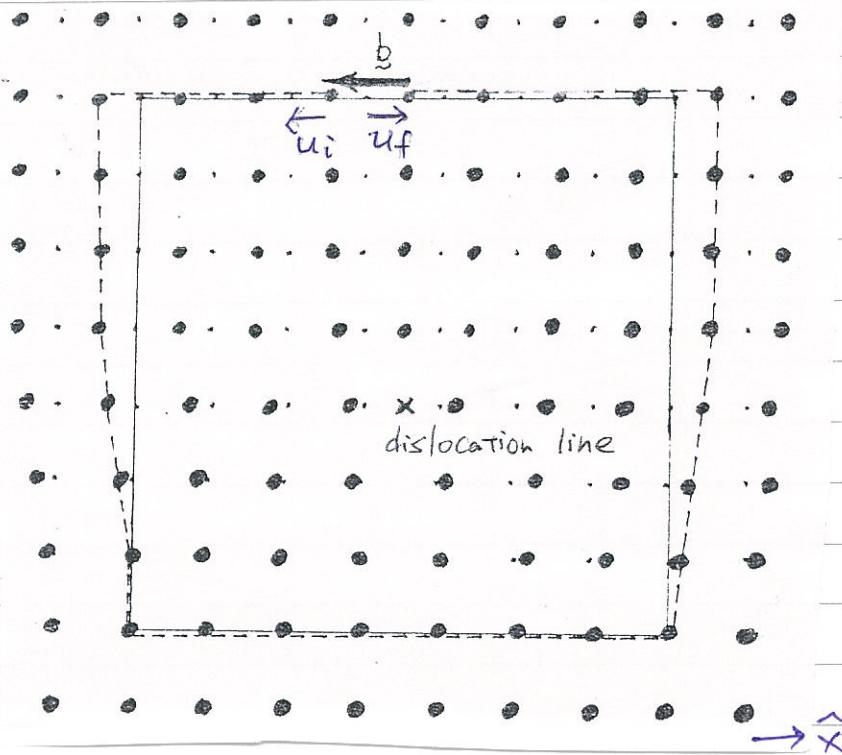
As we have learned, crystal order is not stable in 2D. Then, what is the state of a 2D solid?

Nelson & Halperin proposed that 2D solids are crystals with bound pairs of dislocations and disclinations. (Phys. Rev. 19, 2457, 1979)

The theory represents the view of liquid-solid transition from the solid side.

Burgers vector: To describe the melting from the 2D.

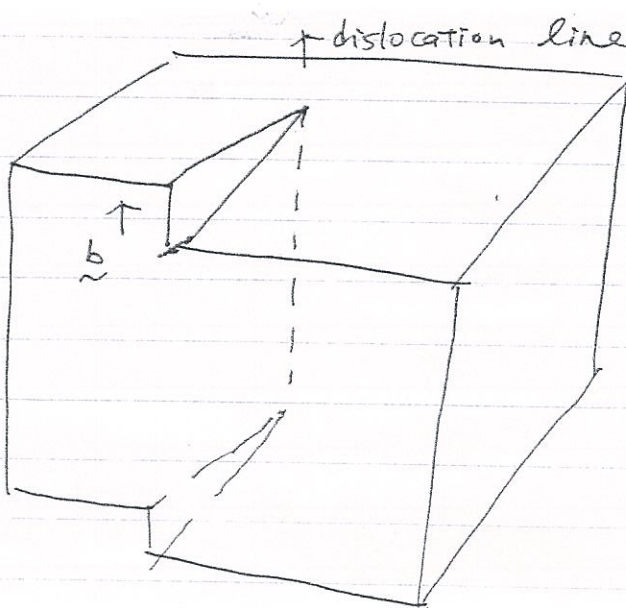
solid side, one needs to characterize the dislocations. Dislocations are characterized by the Burgers vector as shown below.



$\vec{b}$  = Burgers vector  
= net displacement  
along a circle encircle  
the edge dislocation

$\vec{b} \perp$  dislocation line  
for edge dislocations

$$\oint d\vec{u} = \vec{u}_f - \vec{u}_i = \vec{b} = -b \hat{x}$$



For screw dislocations  
as shown in the  
left figure,

$\vec{b} \parallel$  dislocation line



## 2D dislocations & their interactions

In 2D, one has edge dislocations.

The displacement field  $\vec{u}$  without <sup>any</sup> dislocation

satisfies  $\frac{\partial \epsilon_{\alpha\beta}}{\partial x_\beta} = 0$ ,  $\sigma_{\alpha\beta} = \lambda \delta_{\alpha\beta} \nabla \cdot \vec{u} + 2\mu \epsilon_{\alpha\beta}$

$$(\lambda + \mu) \nabla (\nabla \cdot \vec{u}) + \mu \nabla^2 \vec{u} = 0$$

--- (9)

in static situation.

This, however, is no longer true in presence

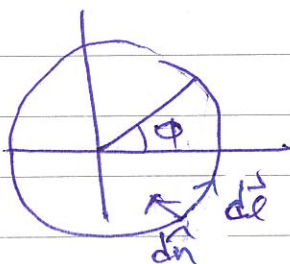
of a dislocation. One expects source term

with  $\delta$  function would arise.

To get the equation for a single

dislocation, we start by considering the

integration of angle  $\phi = \tan^{-1} y/x$



clearly  $\oint \nabla \phi \cdot d\vec{e}$

$$= \oint d\phi = 2\pi$$

$\therefore$  if  $\phi = \frac{\theta}{2\pi} \tan^{-1} y/x$

$$\oint \nabla \phi \cdot d\vec{e} = \theta \quad \text{--- (10)}$$

Now,  $\tan^{-1}y/x$  is the imaginary part of  $\ln z$ .

with  $z = x + iy$ .

$$\ln z = \underbrace{\ln|z|}_u + i\phi$$

From complex analysis, we know  $\frac{\partial v}{\partial x} = \frac{\partial \phi}{\partial y}$ ,  $\frac{\partial v}{\partial y} = -\frac{\partial \phi}{\partial x}$

$$\begin{aligned} \therefore \nabla \phi \cdot d\vec{e} &= \left( \frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y} \right) (dx, dy) \\ &= \left( +\frac{\partial v}{\partial x} dy - \frac{\partial v}{\partial y} dx \right) = \left( \frac{\partial v}{\partial x}, \frac{\partial v}{\partial y} \right) \cdot (dy, -dx) \\ &= \vec{n} \cdot d\vec{u} \end{aligned}$$

Therefore, eq. (10)  $\Rightarrow \oint \vec{\nabla} v \cdot d\vec{u} = g$

$$\int \nabla^2 v - d^2 v = g$$

We get the differential form of eq. (10)

$$\nabla^2 v = g f(r) \quad (11)$$

In terms of  $\phi$ :  $\frac{\partial^2 \phi}{\partial x \partial y} - \frac{\partial^2 \phi}{\partial y \partial x} = g f(r) \dots$

Now, for an edge dislocation with Burgers vector  $\vec{b}$

$$\therefore \oint \nabla u^\alpha \cdot d\vec{e} = \oint du^\alpha = b^\alpha a_0 \quad a_0 = \text{lattice constant}$$

We find  $\frac{\partial u^\alpha}{\partial x \partial y} - \frac{\partial u^\alpha}{\partial y \partial x} = b^\alpha a_0 f(r)$

i.e.  $\left\{ \begin{aligned} \frac{\partial^2 u^x}{\partial x \partial y} - \frac{\partial u^x}{\partial y \partial x} &= b^x a_0 f(r) \quad \dots (12) \\ \frac{\partial^2 u^y}{\partial x \partial y} - \frac{\partial u^y}{\partial y \partial x} &= b^y a_0 f(r) \quad \dots (13) \end{aligned} \right.$

That is, differentiation with respect to  $x$  and  $y$  can not be exchanged.

In this case,  $\frac{d\phi_{\alpha\beta}}{dX_{\beta}} = 0$  does not reduce to eq. (9).

Instead,  $\therefore \frac{d\phi_{\alpha\beta}}{dX_{\beta}} = \lambda \frac{d}{dX_{\alpha}} (\vec{\nabla} \cdot \vec{u}) + 2\mu \frac{d}{dX_{\beta}} \epsilon_{\alpha\beta}$

we find

$$\mu \frac{d}{dX_{\beta}} \left( \frac{d^2 u_{\alpha}}{dX_{\beta} dX_{\beta}} \right) + \mu \frac{d^2 u_{\beta}}{dX_{\beta} dX_{\alpha}} + \lambda \frac{d}{dX_{\alpha}} (\vec{\nabla} \cdot \vec{u}) = 0$$

The term  $\mu \frac{d^2 u_{\beta}}{dX_{\beta} dX_{\alpha}}$  =  $\mu \frac{d^2 u_x}{dX_{\beta} dX_{\alpha}} + \mu \frac{d^2 u_y}{dY_{\beta} dX_{\alpha}}$  for  $\alpha=1$   
 $\downarrow$  exchange  $x \leftrightarrow y$   
 $= \mu \frac{d^2 u_x}{dX_{\alpha} dX_{\beta}} + \mu \frac{d^2 u_y}{dX_{\alpha} dY_{\beta}} - b^b a_0 \delta(\mathcal{R}^2)$   
 $= \mu \frac{d}{dX_{\alpha}} \vec{\nabla} \cdot \vec{u} - b^b a_0 \delta(\mathcal{R}^2)$

$\alpha=2$ ,  $\mu \frac{d^2 u_{\beta}}{dY_{\beta} dX_{\alpha}} = \mu \frac{d^2 u_x}{dX_{\alpha} dY_{\beta}} + \mu \frac{d^2 u_y}{dY_{\beta} dY_{\alpha}}$   
 $= \mu \frac{d^2 u_x}{dY_{\beta} dX_{\alpha}} + \mu \frac{d^2 u_y}{dY_{\beta} dY_{\alpha}} + b^x a_0 \delta(\mathcal{R}^2)$   
 $= \mu \frac{d}{dY_{\beta}} \vec{\nabla} \cdot \vec{u} + b^x a_0 \delta(\mathcal{R}^2)$

$\therefore \mu \frac{d^2 u_{\beta}}{dY_{\beta} dX_{\alpha}} = \nabla_{\alpha} (\vec{\nabla} \cdot \vec{u}) + \vec{b}_{\alpha}^{\perp} a_0 \delta(\mathcal{R}^2)$ ,  $\vec{b}^{\perp} = (-b^y, b^x)$

we get

$$\nabla^2 \vec{u} + \frac{\lambda + \mu}{\mu} \nabla (\vec{\nabla} \cdot \vec{u}) = -\vec{b}^{\perp} a_0 \delta(\mathcal{R}^2) \quad (14)$$

It's important see that  $\vec{u}(\vec{r})$  due to a dislocation is logarithmic.

For this purpose, we consider  $\vec{u}^0$  such that

$$\nabla \cdot \vec{u}^0 = 0, \quad \text{then} \quad \nabla^2 \vec{u}^0 = -\vec{b}^\perp a_0 \delta(\vec{r})$$

$$\vec{u}^0 = -\frac{a_0 \vec{b}^\perp}{2\pi} \ln \frac{r}{a_0} \quad (\nabla^2 \ln r = 2\pi \delta(\vec{r}))$$

The energy for a single dislocation is then

$$E_e = \frac{1}{2} \int d^2r \left[ \underbrace{2\mu}_{\frac{\mu}{2} \left( \frac{\partial u_\alpha}{\partial x_\beta} + \frac{\partial u_\beta}{\partial x_\alpha} \right)^2} \epsilon_{\alpha\beta}^2 + (\mu + \lambda) (\nabla \cdot \vec{u})^2 \right]$$

$$= \frac{1}{2} \mu \int d^2r \left( \frac{\partial u_\alpha}{\partial x_\beta} \right)^2$$

$$\frac{\partial u_\alpha}{\partial x_\beta} \frac{\partial u_\beta}{\partial x_\alpha} \rightarrow 0$$

$$= \frac{1}{2} \mu \left( \frac{a_0}{2\pi} \right)^2 \sum_{\alpha} (b_{\perp}^{\alpha})^2 \int d^2r (\nabla \ln \frac{r}{a_0})^2$$

$$= \frac{1}{2} \mu \left( \frac{a_0}{2\pi} \right)^2 b_{\perp}^2 \int_{a_0}^R 2\pi r dr \left( \frac{1}{r} \right)^2$$

$$= \frac{1}{2} \mu \left( \frac{a_0 b_{\perp}}{2\pi} \right)^2 \times 2\pi \ln \frac{R}{a_0} \propto b^2 !$$

For  $n$  dislocations,  $\nabla^2 \vec{u}^0 = -\vec{b}_i^\perp a_0$

$$\vec{u}^0 = \frac{a_0 \vec{b}_1^\perp}{2\pi} \ln \left| \frac{r - \vec{r}_1}{a_0} \right| + \frac{a_0 \vec{b}_2^\perp}{2\pi} \ln \left| \frac{r - \vec{r}_2}{a_0} \right|$$

$$\begin{aligned} & \times \delta(r - \vec{r}_1) \\ & - \vec{b}_i^\perp a_0 \delta(r - \vec{r}_i) \end{aligned}$$

$$E = \frac{1}{2} \mu \int d^2r \left( \frac{\partial u_\alpha}{\partial x_\beta} \right)^2 = \frac{1}{2} \mu \int d^2r \vec{u} \cdot \nabla^2 \vec{u}$$

$$\sim \frac{1}{2} \mu \left( \frac{a_0}{2\pi} \right)^2 \sum_i (b_i^\perp)^2 \ln \left| \frac{r - \vec{r}_i}{a_0} \right|$$

Hence, dislocations in 2D interact through

$$\ln \left| \frac{r-r'}{a} \right| \text{ potential!}$$

In general, if one does not restrict to

$$\nabla \cdot \vec{u} = 0, \text{ one finds}$$

$$\frac{F}{k_B T} = - \frac{1}{\beta A} \sum_{r \neq r'} k_1 \vec{b}(r) \cdot \vec{b}(r') \ln \left| \frac{r-r'}{a_0} \right|$$

$$- k_2 \frac{[\vec{b}(r) \cdot (r-r')] [\vec{b}(r') \cdot (r-r')]}{|r-r'|^2}$$

$$+ \frac{E_c}{k_B T} \sum_r |\vec{b}(r)|^2 \dots \quad (15)$$

(Nelson & Halperin)

$E_c =$  creation energy for a unit dislocation

Since  $\underbrace{\text{large } b}$  is large, we can restrict creation energy for

ourselves to small  $b$ , i.e., dislocations with

unit Burgers vector  $\pm \vec{a}_0$

Furthermore, we require  $\sum_r \vec{b}(r) = 0$  because

there is no overall slip of the crystal.

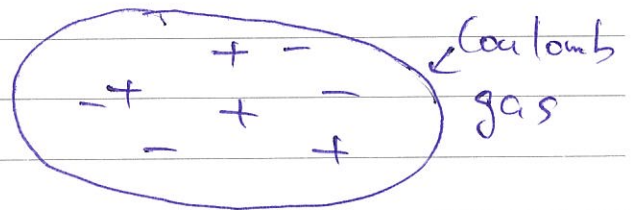
The dominant interaction for 2D dislocations

is log-range log interaction. This is

also known as 2D Coulomb gas with

$$H' = \frac{1}{2} \sum_{i \neq j} q_i q_j \ln \frac{|\vec{r}_i - \vec{r}_j|}{a} \quad q_i = \pm q$$

$$\sum_i q_i = 0 \quad (\text{neutral})$$

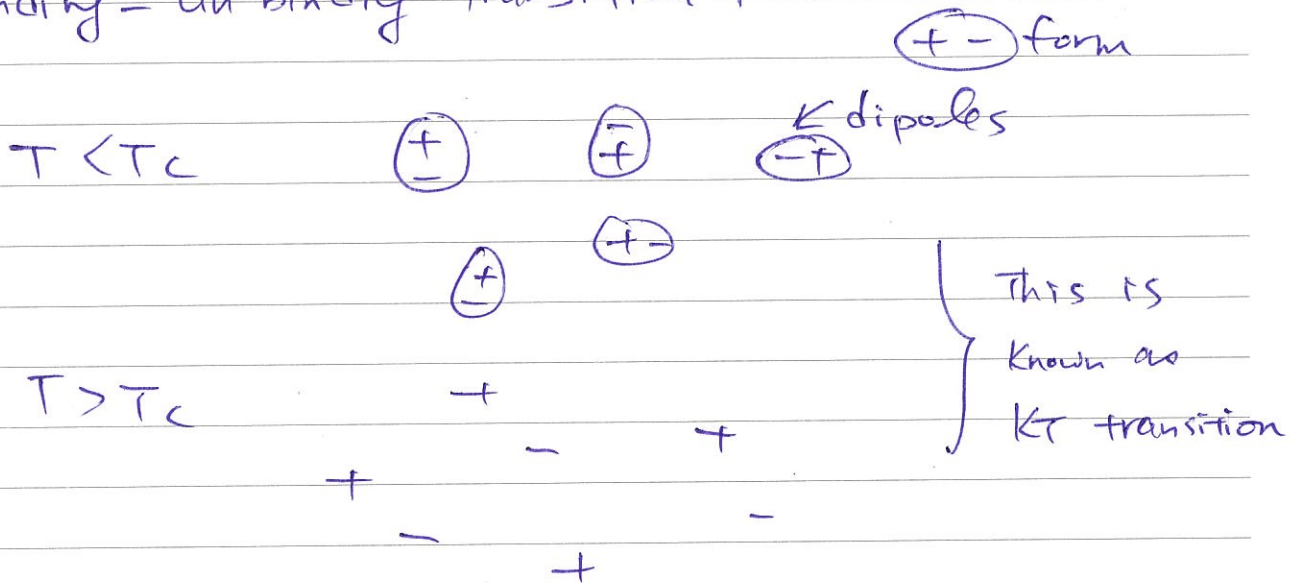


Kosterlitz & Thouless

(J. Phys. C 5, L124, 1972, C6, 1141, 1973)

solved this system <sup>by</sup> using so-called renormalization group method and found that it is

binding - unbinding transition:



To estimate  $T_c$ , we define

$$\phi = -q \ln \left| \frac{r}{a} \right| \quad \therefore \nabla^2 \phi = -2\pi q \delta(\vec{r})$$

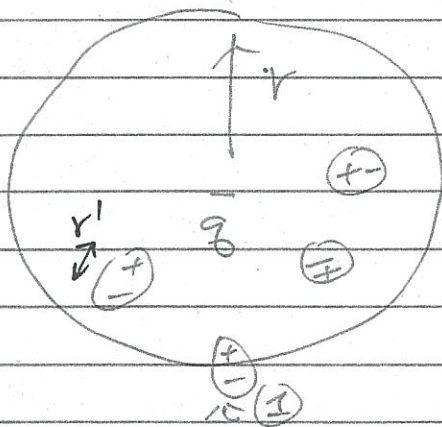
if  $r \rightarrow \infty$ , after screening, we expect

$$\phi = -\frac{q_0}{\epsilon} \ln \frac{r}{a}, \quad \epsilon(r \rightarrow \infty) \neq 0$$

$\Rightarrow$   $(+ -)$  bind together  $\therefore$  still strongly interaction attraction!

if  $\frac{1}{\epsilon} \rightarrow 0$ , free vortices!

Let us look at one vortex:



if  $(+) < r$

total charge inside  $r$  ( $-\frac{q_0}{\epsilon}$ )

is almost the same as  $q_0$

Only dipoles such as  $(\pm)$  contribute to charge total charge, but this finite!

$\therefore$  To create screening,  $(+) < r$  has to  $> r$ !

size of

Suppose, we have picked up the 1st charge, the probability distribution (per area) for picking up

the other partner  $P(r') \propto e^{-\frac{q^2}{k_B T} \ln \frac{r'}{a'}} = \left(\frac{r'}{a'}\right)^{-\frac{q^2}{k_B T}}$

$\therefore$  total probability per unit area for  
charge's location

$$= \int_r^\infty dr' 2\pi r' P(r')$$

$\therefore$  # of dipoles with one charge  $< r$

the other charge  $> r$

$$\propto (\pi r^2) \int_r^\infty 2\pi r' dr' \left(\frac{r'}{a'}\right)^{-\frac{q^2}{k_B T}}$$

probability

for picking up the 1st charge

$$\propto r^4 - \frac{q^2}{k_B T}$$

$$\therefore T < T_c \cong \frac{q^2}{4k_B} \sim \frac{b^2}{4k_B} \rightarrow 0 \text{ as } r \rightarrow \infty$$

$\therefore$  dipoles combined!

otherwise,  $T > T_c$ , dipoles dissociate!



Because dislocations are associated with additional half row of atoms, they are quite effective at breaking up translational order. Hence binding-unbinding of dislocations describes transition of translational order!

harmonic solid  $\xrightarrow{\quad}$

binding of dislocations  $T_M = T_C$  unbinding of dislocations  
 translational order  $\checkmark$  (quasi-long range order)  $\times$

$$\langle \rho_S(\vec{r}) \rho_S(\vec{0}) \rangle$$

$$\sim \frac{1}{r^{1/3}} \quad \langle (\vec{u}_i - \vec{u}_j)^2 \rangle \sim \ln \frac{|\vec{r}_i - \vec{r}_j|}{a}$$

(harmonic waves)

$T < T_C$ , dislocations bind

Above  $T_M = T_C$ , dislocations <sup>un</sup>bind

$$\langle (\vec{u}_i - \vec{u}_j)^2 \rangle$$

$$\ln |\vec{r}_i - \vec{r}_j| \quad \text{is no longer true!}$$

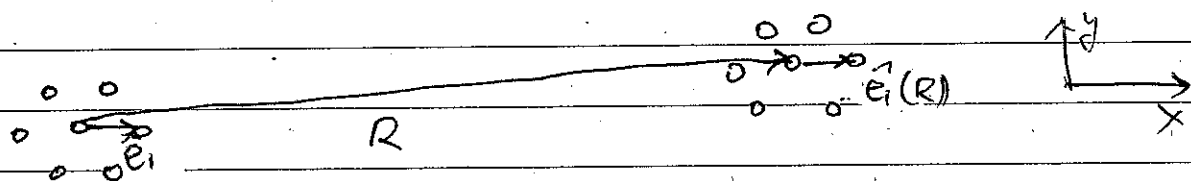
Screening leads to  $\langle \rho_S(\vec{r}) \rho_S(\vec{0}) \rangle \sim e^{-\sqrt{g} r}$

$\therefore$  translational order is broken.

However, as pointed by Nelson & Halperin, this is not the end of the story.

The location of  $G$  reflects the translational invariance of crystals. Therefore, when it disappears, it means the translational order is broken!  
only

Nelson & Halperin points that if one calculates the orientational order, it still persists:



it could happen

$$\vec{R} = m\vec{a} + n\vec{b} \text{ (lattice)}$$

$$\text{but } \hat{e}_i(\vec{R}) \parallel \hat{e}_i$$

To see if  $\hat{e}_i(\vec{R}) \parallel \hat{e}_i$ , one realizes

$$\hat{e}_i = \underbrace{(R_i \hat{e}_i^0 + U_i \hat{e}_i^0)}_{\hat{R}_i \hat{e}_i^0} = \underbrace{(R_i^0 + U_i)}_{R_i}$$

$$\hat{e}_i = \hat{e}_i^0 + (U_i \hat{e}_i^0 - U_i) \hat{e}_i^0$$

$$\text{if } \hat{e}_i^0 \parallel \hat{x}, \text{ then } \sin \theta_{i1} = U_i \hat{e}_i^0 - U_i$$

$$\text{For small } U_i, \theta_{i1} = U_i \hat{e}_i^0 - U_i = \hat{e}_i \cdot (U_i \hat{e}_i^0 - U_i)$$

$$\text{Similarly, } \theta_{i2} = \hat{e}_i \cdot (U_i \hat{e}_i^0 - U_i)$$

The average deviation of hexagon can

be represented by 
$$\theta_i = \frac{1}{6} \sum_{n=1}^6 \theta_{in}$$

$$= \frac{1}{6} \sum_{n=1}^6 \hat{e}_n^{\perp} \cdot (u_{i+\hat{e}_n} - u_i)$$

$$= \frac{1}{6} \sum_{n=1}^6 \hat{e}_n^{\perp} [(\hat{e}_n \cdot \vec{\nabla}) u_i]$$

$$\frac{1}{6} \sum_{n=1}^6 (\hat{e}_n^{\perp})_{\alpha} (\hat{e}_n)_{\beta} = \frac{1}{2} \epsilon_{\alpha\beta} = \frac{1}{2} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

||  
z x  $\hat{e}_n$

||  
$$\frac{1}{2} \times \frac{1}{6} \sum_{n=1}^6 (\hat{e}_n)_{\alpha} (\hat{e}_n)_{\beta} = \frac{1}{2} \times 3 \hat{I} = \frac{1}{2} \hat{z} \times \hat{I} \Rightarrow \frac{1}{2} \epsilon_{\alpha\beta}$$

$$\frac{1}{2} \times (\hat{x}\hat{x}) = \hat{y}\hat{y}, \quad \frac{1}{2} \times (\hat{y}\hat{y}) = -\hat{x}\hat{x}$$

$$\therefore \theta(\mathbf{r}) = \frac{1}{2} \sum_{\alpha\beta} \epsilon_{\alpha\beta} \partial_{\beta} u_{\alpha} = \frac{1}{2} \left( \frac{\partial u^y}{\partial x} - \frac{\partial u^x}{\partial y} \right)$$

$$= \frac{1}{2} (\nabla \times \vec{u}) \cdot \hat{z}$$

$$\therefore \theta(\mathbf{r}) \rightarrow \theta(\mathbf{r}) + \frac{2\pi}{6} \Rightarrow \text{same orientation}$$

$\therefore$  the order parameter can be defined

$$\psi_6(\mathbf{r}) = e^{6i\theta(\mathbf{r})}$$

(bond orientational order)

Its correlation can be defined as

$$g_b(R) = \langle \psi_b(R) \psi_b^*(0) \rangle \\ = \langle e^{i\phi(\theta(R) - \theta(0))} \rangle$$

Obviously, because  $\theta \propto \nabla \times u$ ,  $\therefore \theta$  has a dimension higher than  $u$ . As a result, when  $T > T_M$ ,  $g_b(R) \rightarrow \text{const}$  as  $R \rightarrow \infty$ :

$$g_b(R) = e^{-3b \frac{1}{2} \langle (\theta(R) - \theta(0))^2 \rangle}$$

$$\frac{1}{2} \langle (\theta(R) - \theta(0))^2 \rangle$$

$$= \frac{1}{\rho} \langle (\nabla \times u(R) - \nabla \times u(0))^2 \rangle$$

$$= \frac{1}{\rho} \sum_{\mu\alpha} \sum_{\nu\beta} \rho_{\mu\nu} \langle (u^\alpha(R) - u^\alpha(0))(u^\beta(R) - u^\beta(0)) \rangle$$

$$= \frac{1}{\rho} \sum_{\mu\alpha} \sum_{\nu\beta} \rho_{\mu\nu} \int_{\mathbf{k}} (1 - e^{i\mathbf{k}\cdot\mathbf{R}}) \langle u^\alpha(\mathbf{k}) u^\beta(\mathbf{k}) \rangle$$

eq. (4)

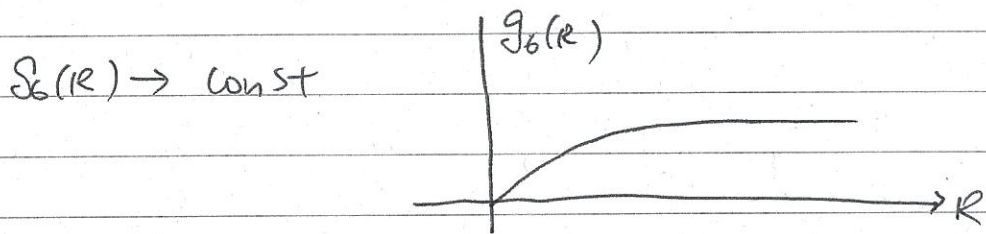
$$= \frac{1}{\rho} \sum_{\mu\alpha} \sum_{\nu\beta} \int_{\mathbf{k}} k^\mu k^\nu (1 - e^{i\mathbf{k}\cdot\mathbf{R}}) \langle u^\alpha(\mathbf{k}) u^\beta(\mathbf{k}) \rangle$$

$$= \frac{1}{\rho} \sum_{\mu\alpha} \sum_{\nu\beta} \int_{\mathbf{k}} \frac{k_B T (1 - e^{i\mathbf{k}\cdot\mathbf{R}})}{k^2} \left[ \frac{\rho_{\alpha\beta}}{c_{66}} + \frac{\rho_{\alpha\beta}}{c_{11}} \right] k^\mu k^\nu$$

$$\therefore \sum_{\mu\alpha} k^\mu k^\alpha = (\vec{k} \times \vec{R}) \cdot \hat{z} = 0; \quad \sum_{\mu\alpha} \sum_{\nu\beta} \rho_{\alpha\beta} k^\mu k^\nu = k^2 \quad \square$$

$$\begin{aligned} \therefore \frac{1}{2} \langle (\theta(R) - \theta(0))^2 \rangle &= \frac{1}{8} \int_K \frac{k_B T}{c^2} (1 - e^{ik \cdot R}) \\ &= \frac{k_B T}{8c^2} (1 - f_{R,0}) \times (2\pi)^3 \end{aligned}$$

$\therefore R \rightarrow \infty \quad \frac{1}{2} \langle (\theta(R) - \theta(0))^2 \rangle = \text{const}$



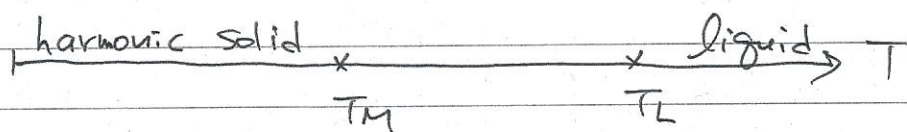
$\therefore$  It still possess long-range orientational order

if  $F$  is given by the harmonic approximation (eq. 2)!

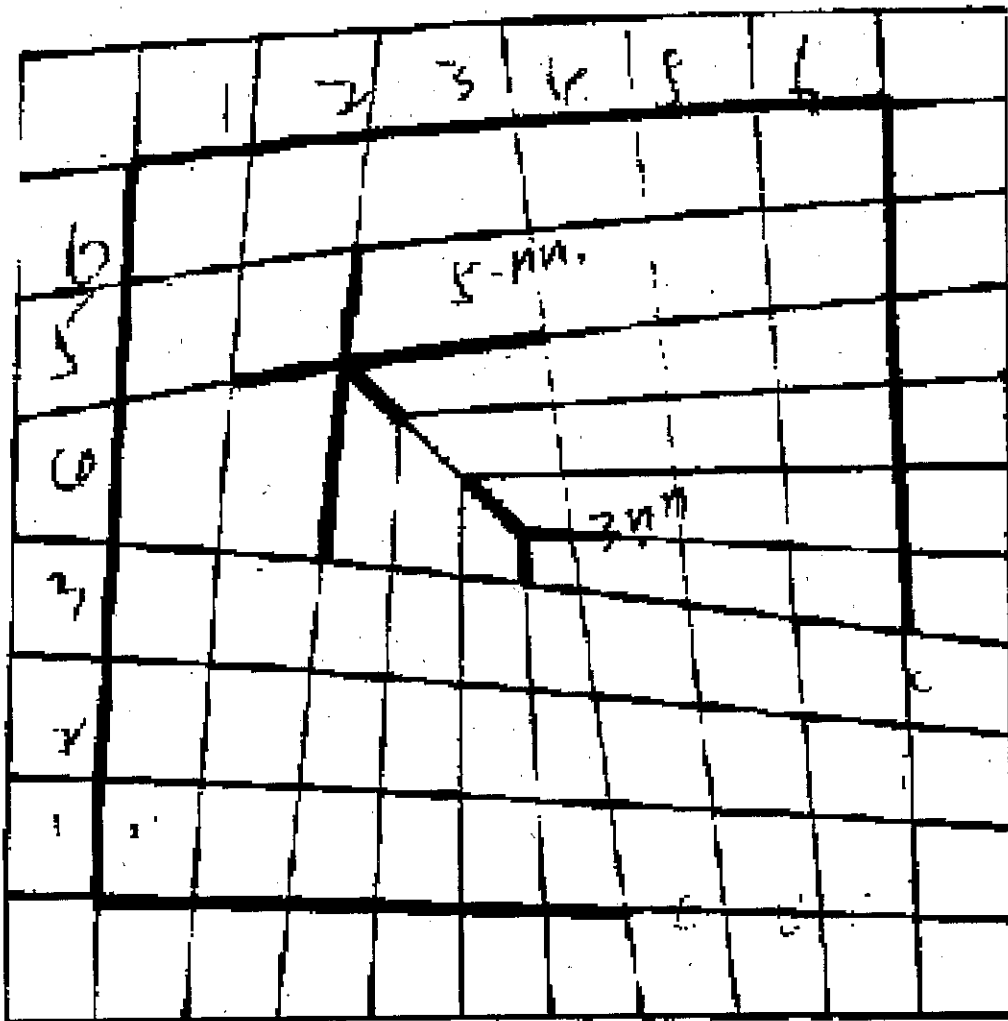
Nelson & Halperin pointed <sup>out</sup> that this is because even though dislocations are free for  $T > T_M$ , each dislocation actually contains a pair of bound disclinations. (see Fig)

What will happen is :

in the next page 7-30

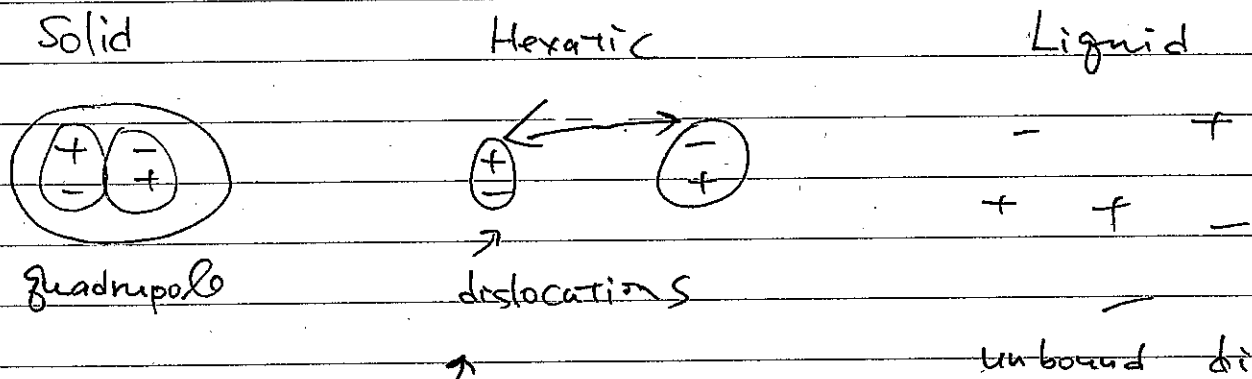


exist an intermediate phase called hexatic phase



Dislocation that may be viewed as a bound disclination pair. A path around the dislocation fails to close, as shown. The two disclinations, one having five nearest neighbors and

①  $T > T_L$ , orientational order breaks down when bound disclinations are free (see Fig 3.) , if we use  $\pm$  to present two disclinations, one gets the following picture:



②

$\langle \rho_6(r) \rho_6(0) \rangle$	$\langle \rho_6(r) \rho_6(0) \rangle$	
$\sim \frac{1}{r^{n_6}}$	$\sim e^{-r/\xi(T)}$	
	$\langle \psi_6(r) \psi_6^*(0) \rangle$	$\langle \psi_6(r) \psi_6^*(0) \rangle$
$\frac{F_D}{k_B T}$	$\sim \frac{1}{r^{n_6}}$	$\sim e^{-r/\xi'}$
$= \frac{-K}{8\pi} \sum_{k \neq 0} \left[ \epsilon(k) \cdot \delta(k) \ln \frac{ r-r' }{a} \right]$		$(\xi' = \xi^2)$
$\left[ \frac{\epsilon(k) \cdot (r-r') \delta(k) \cdot (r-r')}{ r-r' ^2} \right]$	based on the existence of long-range order of $\theta$	
$+ \frac{E_c}{k_B T} \sum_r  \epsilon(r) ^2$		

$\Rightarrow F \propto \int \frac{1}{2} K A d^2 r (\nabla \theta)^2$

③

singularity of  $\theta \Rightarrow$  disclination

$\therefore$  logarithmic interaction too!

$$F_{dis} = \frac{1}{2} K A \int d^2 r (\nabla \theta)^2$$

$$= \frac{\pi K A}{36} \sum_{k \neq 0} S(k) S^*(k) \ln \frac{|r-r'|}{a} + E_c \sum_r S(r)^2$$