

Electrostatics

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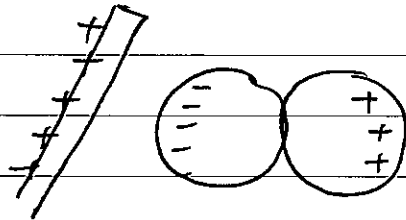
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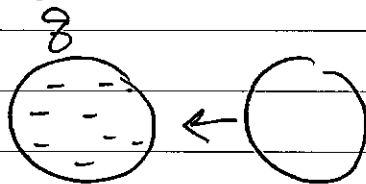
Coulomb's Law

Electric charges were discovered early in human history through rubbing between materials.

Later, it's found that by induction (move a charge object near a conductor), one can charge a conductor (materials made by metal).



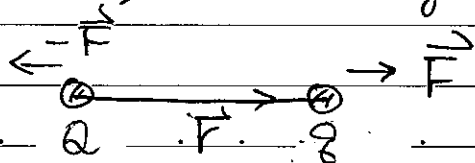
Using method of charging ^{by} induction, one can charge charges on an object:



touch → separate $\frac{q}{2}$ $\frac{q}{2}$

Measuring the force, Coulomb found that

for static, fixed charges ^(point-like) separating by r



$$\vec{F} = k \frac{qQ}{r^2} \hat{r} = k \frac{qQ}{k_3 \epsilon_0 r^2} \hat{r}$$

Eq. ① is the Coulomb's law and it works

only for static charges.

The proportional constant k depends

on unit of charges. Charges are later

known to be quantized $|q| = N|e|$ with

$$|e| = \text{charge magnitude of electron charge} \\ = 1.6 \times 10^{-19} \text{ Coulomb.}$$

In SI unit, the unit of charge is

Coulomb (C) : the amount of charge

that is transferred through the cross section of a wire in 1 second when the current in the wire is 1 Ampere.

In this unit,
$$k = \frac{1}{4\pi\epsilon_0} = 8.99 \times 10^9 \text{ Nm}^2/\text{C}^2$$

with $\epsilon_0 \equiv$ permittivity of free space

$$= 8.85 \times 10^{-12} \frac{\text{C}^2}{\text{Nm}^2}$$

There are other unit systems such as

Gaussian, $k=1$, Heaviside-Lorentz, $k=\frac{1}{4\pi}$

we shall not use them in this (elementary particle physics) course.

Principle of Superposition

For static charges, it's found that

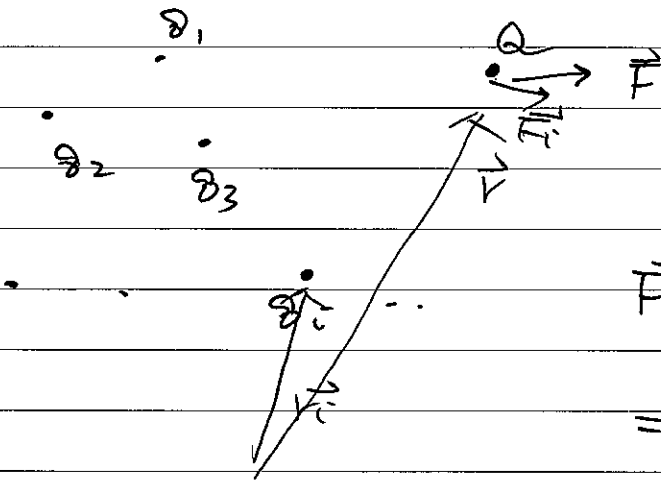
the interaction between any two charges

is not affected by the presence of others.

Therefore, if Q is a test charge,

the ^{net} force that acts on Q due to

$q_1, q_2, \dots, q_i, \dots$ (source charges) is sum of individual force \vec{F}_i that acts on Q



$$\vec{F} = \vec{F}_1 + \vec{F}_2 + \dots$$

$$= \frac{1}{4\pi\epsilon_0} \frac{q_1 Q}{|\vec{r} - \vec{r}_1|^3} (\vec{r} - \vec{r}_1) + \dots \quad (2)$$

$$+ \frac{1}{4\pi\epsilon_0} \frac{q_2 Q}{|\vec{r} - \vec{r}_2|^3} (\vec{r} - \vec{r}_2)$$

$$+ \dots + \frac{1}{4\pi\epsilon_0} \frac{q_3 Q}{|\vec{r} - \vec{r}_3|^3} (\vec{r} - \vec{r}_3) + \dots$$

This is the principle of superposition, which

is also valid generally when charges are moving and not static.

The principle of superposition, in particular,

implies ^{that} the system is linear (in \mathcal{E}_i)

and we shall see that a lot of

simplification in describing EM interaction

is due to this feature.

Electric field

As we discussed in the introduction, the

reality behind the Coulomb's law is that

charges has already change the property
the presence of

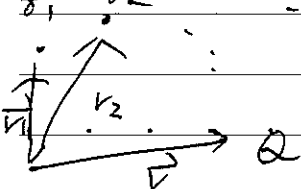
of the space so that when another

charge, called test charge Q , is introduced

at \vec{r} , it is affected by the field \vec{E}

at \vec{r} so that a force, $\vec{F}_Q = Q\vec{E}(\vec{r})$,

acts on Q .



$$\vec{E}(\vec{r}) = \frac{\vec{F}_Q(\vec{r})}{Q} = \frac{1}{4\pi\epsilon_0} \sum_i \frac{q_i}{|\vec{r}-\vec{r}_i|^3} (\vec{r}-\vec{r}_i) \quad (3)$$

Clearly, such defined $\vec{E}(\vec{r})$ depends only
 indeed

on source charges and doesn't depend

on Q .

$\vec{E}(\vec{r})$ is consistent with the idea of properties

produced at \vec{r} due to source charges.

And this is possible only when the superposition principle works.

Continuous charge distribution

In reality, charges may have sizes

and magnitudes of charges are

quantized. $Q = Ne$ i.e., not all values of Q are allowed.

However, it is still convenient to consider charges as continuous charge distribution.

In this case, one first realizes that each

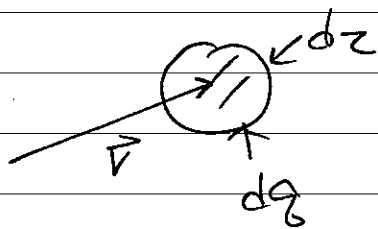
mathematical space point (displacement) \vec{r} has

no size. The charge density (3D) at any

Point P is defined by taking a small

volume $d\tau$ centered at P and

dQ is charge inside $d\tau$, then

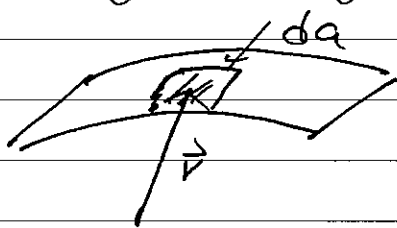


$$\rho(P) \equiv \lim_{d\tau \rightarrow 0} \frac{dQ(P)}{d\tau}$$

Similarly, if charges distribute only on

surfaces, one considers a small area

da centered at P , with the total charge inside da . The surface charge density (charge/area),

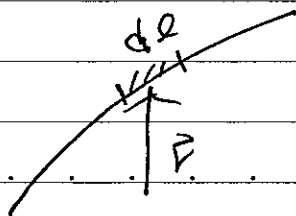


$$\sigma(P) \equiv \lim_{da \rightarrow 0} \frac{dQ(P)}{da}$$

(面密度)

If the charge is spread out along a line,

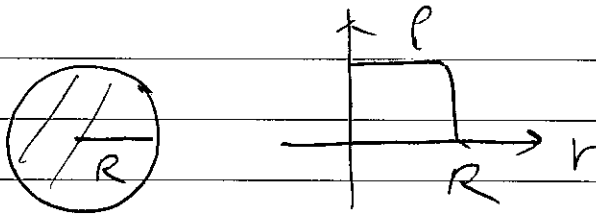
one considers a small segment $d\ell$ with dQ inside, the line charge density λ (charge per unit length)



$$\lambda(P) \equiv \lim_{d\ell \rightarrow 0} \frac{dQ(P)}{d\ell}$$

The continuous charge distribution can describe charges even when the charged particle has a finite size & charge is quantized.

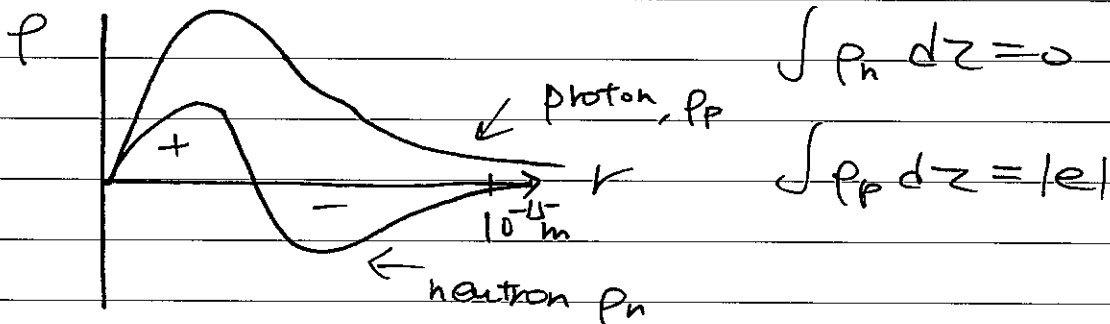
In this case, one may have



$R =$ size of charge

$$\int \rho dz = \int dq = Ne$$

example: neutron & proton



Point charge & Dirac Delta function

A natural question arises: do all charged particles have finite sizes?

It turns out that some elementary particles $r < 10^{-22} \text{ m}$ appears to be point-like (such as electrons). They may eventually have structures (such as string --) but for practical purposes, it is

Convenient to treat them as idealized

mathematical points and are termed as

point charges. In order to describe

charge densities for these charges, Dirac

devised a mathematical object, called

Dirac delta function, to the charge density.

To describe ^{point} charges with general magnitudes,

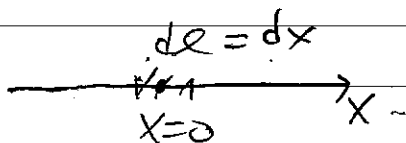
it's suffice to describe charges with

magnitude being 1.

For point charges on 1D, clearly,

Since there is no size, $dq = 1$ for

any dx including the charge. If the



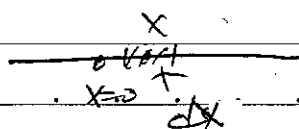
Charge is located at $x=0$,

we have

$$\lambda(x=0) = \lim_{\substack{dq \rightarrow 0 \\ dx}} \frac{dq}{dx} = \lim_{dx} \frac{1}{dx} = \infty$$

However, at $x \neq 0$, if d is small enough,

$dq = 0$

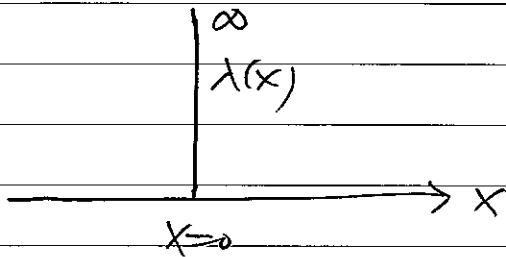


$$\lambda(x \neq 0) = \lim_{dq \rightarrow 0} \frac{dq}{dx} = 0$$

Therefore, the charge density $\lambda(x)$ is

very singular : $\lambda(x=0) = \infty$

$\lambda(x \neq 0) = 0$



However, \therefore total charge $q = 1$,

$$\therefore \int dq = \int dx \cdot \lambda(x) = 1$$

$$\therefore \int dx \lambda(x) = 1 \quad (dx = dq)$$

Such function is called one-dimensional Dirac delta

function, denoted by $\delta(x)$ or $\delta(x-a)$

if the charge is located at $x=a$

Clearly, for ^{1D} point charges of magnitude q , $\lambda(x) = q \delta(x)$

The Dirac delta function is actually not

a function at all since its value at

$x=0$ (or $x=a$) is not finite

In the mathematical language, it is

known as a generalized function or

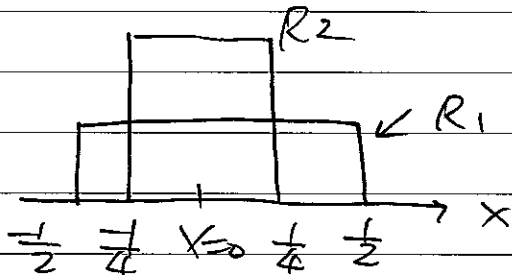
distribution (linear functionals, see below)

It can be considered as the limit of

a sequence of functions

For example, one can consider $f(x)$ as

$$\left. \begin{aligned} \text{limiting of } R_n(x) &= n & |x| \leq \frac{1}{2n} \\ &= 0 & |x| > \frac{1}{2n} \end{aligned} \right\} n \rightarrow \infty$$



$$\int R_n(x) dx = 1$$

$$f(x) = \lim_{n \rightarrow \infty} R_n(x)$$

Using $R_n(x)$, one can find

$$\int_{-\infty}^{\infty} f(x) dx \quad \text{for any ordinary function } f(x)$$

$$= f(0) \dots \textcircled{4}$$

Formally, this is obtained by considering

$$\lim_{n \rightarrow \infty} \int f(x) R_n(x) dx \quad \text{Since } R_n \text{ is non-vanishing}$$

only at $x=0$ $n \rightarrow \infty$, \therefore one gets $\lim_{n \rightarrow \infty} \int_{-\infty}^{\infty} f(x) R_n(x) dx = f(0)$ $\textcircled{5}$

$$\therefore \int_{-\infty}^{\infty} f(x) \delta(x) dx = f(0)$$

Similarly, one can shift $\delta(x)$ to $\delta(x-a)$

and obtains
$$\int_{-\infty}^{\infty} f(x) \delta(x-a) dx = f(a) \dots \textcircled{5}$$

Note that δ function is defined to be independent of which sequence δ_n

taken under the limit $n \rightarrow \infty$, as long

as it gives
$$\lim_{n \rightarrow \infty} \int_{-\infty}^{\infty} f(x) \delta_n(x) dx = f(0)$$

$$\lim_{n \rightarrow \infty} \delta_n(x)$$
 is defined as $\delta(x)$

Mathematically, distribution is defined

as a mapping of $f \rightarrow R$ for any f

Eg. $\textcircled{5}$ is such an example: it depends

on the whole function $f(x)$ and maps

to $f(a)$. This is known as functionals
($\equiv \delta(f)$)

In mathematics

example. $f(kx) = \frac{1}{|k|} f(x)$

consider $I = \int_{-\infty}^{\infty} f(x) \delta(kx) dx$

change of variable. $y = kx$

$k > 0$. $I = \int_{-\infty}^{\infty} f\left(\frac{y}{k}\right) \delta(y) \frac{1}{k} dy$

$$= \frac{1}{k} \int_{-\infty}^{\infty} f\left(\frac{y}{k}\right) \delta(y) dy = \frac{1}{k} f(0)$$

$k < 0$. $I = \int_{\infty}^{-\infty} f\left(\frac{y}{k}\right) \delta(y) \frac{1}{k} dy$

$$= - \int_{-\infty}^{\infty} \frac{1}{k} f\left(\frac{y}{k}\right) \delta(y) dy = -\frac{1}{|k|} f(0)$$

$$\therefore I = \frac{f(0)}{|k|} = \frac{1}{|k|} \int_{-\infty}^{\infty} f(x) \delta(kx) dx$$

$$\therefore \delta(kx) = \frac{1}{|k|} \delta(x)$$

Dirac delta function in higher dimensions

Clearly, 1D $\delta(x)$ can be generalized to 2D & 3D, denoted by $\delta(\vec{r}-\vec{a})$ in general.

Here \vec{r} & \vec{a} are 2D or 3D vectors dependy on dimensions involved.

Eq. (5) is generalized to

$$\int f(\vec{r}) f(\vec{r}-\vec{a}) d\vec{z} = f(\vec{a})$$

--- (6)

$$\text{or } \int f(\vec{r}) f(\vec{r}-\vec{a}) \underset{\substack{\uparrow \\ \text{area}}}{dA} = f(\vec{a})$$

Now, since $d\vec{z} = dx dy dz$ &

$$\begin{aligned} \int f(\vec{r}) f(\vec{r}-\vec{a}) d\vec{z} &= \int dx \int dy \int dz f(x, y, z) f(\vec{r}-\vec{a}) \\ &= f(a_x, a_y, a_z), \quad \vec{a} = (a_x, a_y, a_z), \end{aligned}$$

$f(\vec{r}-\vec{a})$ picks up $x=a_x, y=a_y, \& z=a_z$.

$$\therefore f(a_x, a_y, a_z) = \int dx f(x, a_y, a_z) f(x-a_x)$$

$$= \int dx f(x-a_x) \int dy f(x, y, a_z) f(y-a_y)$$

$$= \int dx \int dy f(x-a_x) f(y-a_y) \int dz f(x, y, z) f(z-a_z)$$

$$\therefore f(\vec{r}-\vec{a}) = f(x-a_x) f(y-a_y) f(z-a_z)$$

Similarly, for $z=0$, $f(\vec{r}) = f(x) f(y)$.

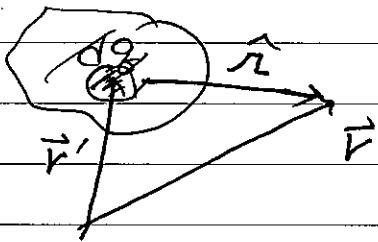
$$f(\vec{r}-\vec{a}) = f(x-a_x) f(y-a_y)$$

Electric field of continuous charge distribution

Given a charge distribution, one can

find the corresponding $\vec{E}(\vec{r})$

$$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{1}{r^2} \hat{r} dq(\vec{r}')$$



$$dq(\vec{r}') = \rho(\vec{r}') d\tau' \quad 3D$$

$$= \sigma(\vec{r}') da' \quad 2D$$

$$= \lambda(\vec{r}') dl' \quad 1D$$

$$\therefore \vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{1}{r^2} \hat{r} \rho(\vec{r}') d\tau'$$

$$= \frac{1}{4\pi\epsilon_0} \int \frac{1}{|\vec{r} - \vec{r}'|^3} (\vec{r} - \vec{r}') \rho(\vec{r}') d\tau' \quad \text{--- (7)}$$

$$\text{or. } \int = \frac{1}{4\pi\epsilon_0} \int \frac{1}{r^2} \hat{r} \sigma(\vec{r}') da'$$

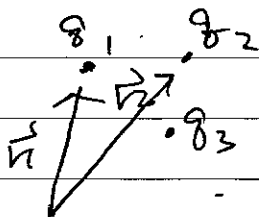
$$= \frac{1}{4\pi\epsilon_0} \int \frac{1}{r^2} \hat{r} \lambda(\vec{r}') dl'$$

Example:

For point charges, $\rho(\vec{r}) = q_1 \delta(\vec{r} - \vec{r}_1) + q_2 \delta(\vec{r} - \vec{r}_2)$

(q_1, q_2, \dots)

+ ... + $q_i \delta(\vec{r} - \vec{r}_i) + \dots$



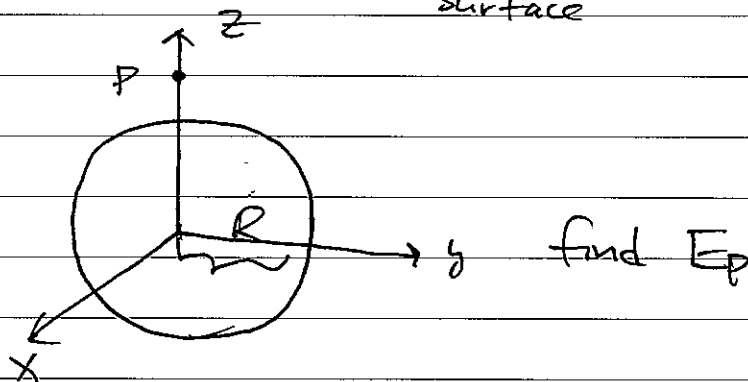
$$= \sum_i q_i \delta(\vec{r} - \vec{r}_i)$$

$$\vec{E}(\vec{r}') = \frac{1}{4\pi\epsilon_0} \int dz' \frac{1}{|\vec{r}-\vec{r}'|^3} (\vec{r}-\vec{r}') (\sigma_1 \delta(r-r_1) + \sigma_2 \delta(r-r_2) + \dots)$$

$$= \frac{1}{4\pi\epsilon_0} \left(\frac{\sigma_1}{|\vec{r}-\vec{r}_1|^3} (\vec{r}-\vec{r}_1) + \frac{\sigma_2}{|\vec{r}-\vec{r}_2|^3} (\vec{r}-\vec{r}_2) + \dots \right)$$

Which recovers eq. (3)

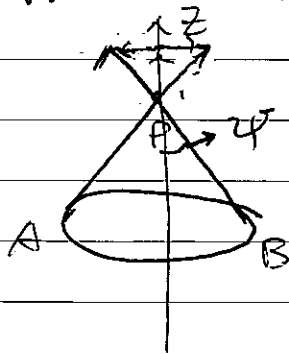
Example Uniformly charged sphere
Surface



Surface charge density
 $= \sigma$

find E_p

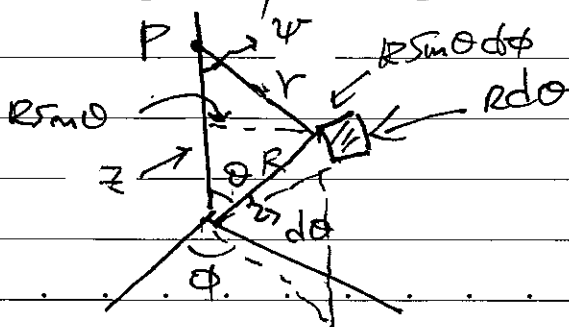
Sol: Consider a ring on sphere, clearly



any pair of points (A & B),
opposite

their E_x & E_y 's cancel against
each other

\therefore One only needs to consider E_z .



For each part on sphere,
it's convenient to use

Spherical Coordinates. (R, θ, ϕ)

The small area = $R d\theta \cdot R \sin\theta d\phi$.

$$\therefore dq = R^2 \sin\theta d\theta d\phi \cdot \rho$$

The E_z contributed by dq

$$dE_z = \frac{1}{4\pi\epsilon_0} \frac{dq}{r^3} \cos\psi$$

$$\therefore E_p = \int dE_z = \frac{1}{4\pi\epsilon_0} \int_0^\pi \sin\theta R^2 d\theta \int_0^{2\pi} d\phi \cdot \cos\psi \cdot \frac{1}{r^2}$$

Now, one needs to express r & ψ in terms of θ & ϕ :

$$\therefore r^2 = R^2 + z^2 - 2Rz \cos\theta$$

$$r \cos\psi = z - R \cos\theta$$

$$\therefore \frac{\cos\psi}{r^2} = \frac{1}{r^3} (z - R \cos\theta) = \frac{z - R \cos\theta}{(R^2 + z^2 - 2Rz \cos\theta)^{3/2}}$$

$$E_p = \frac{\rho R^2}{4\pi\epsilon_0} \times 2\pi \int_0^\pi \frac{(z - R \cos\theta) \sin\theta d\theta}{[R^2 + z^2 - 2Rz \cos\theta]^{3/2}}$$

$$\int_0^{2\pi} d\phi = 2\pi \quad \text{Set } \cos\theta = w \quad \sin\theta d\theta = -dw$$

$$\therefore \int_0^\pi \frac{(z - R \cos\theta) \sin\theta d\theta}{[R^2 + z^2 - 2Rz \cos\theta]^{3/2}} = \int_{-1}^1 \frac{z - Rw}{[R^2 + z^2 - 2Rz w]^{3/2}} dw$$

$$= \frac{1}{z^2} \frac{zW - R}{(R^2 - z^2 - zRzW)^{1/2}} \left| \begin{array}{l} W=1 \\ W=-1 \end{array} \right.$$

$$= \frac{1}{z^2} \left(\frac{z-R}{|z-R|} + \frac{z+R}{|z+R|} \right)$$

$$\therefore E_p = \frac{1}{4\pi\epsilon_0} \frac{z\lambda R^2}{z^2} \left\{ \frac{z-R}{|z-R|} + \frac{z+R}{|z+R|} \right\}$$

$$z > R. \quad \frac{z-R}{|z-R|} = 1, \quad \frac{z+R}{|z+R|} = 1$$

$$E_p = \frac{1}{4\pi\epsilon_0} \frac{z\lambda R^2}{z^2} \times 2 \quad \vec{E}_p = \frac{1}{4\pi\epsilon_0} \frac{\lambda}{z^2} \hat{z}$$

$\therefore 4\pi R^2 \lambda = q$ \rightarrow \vec{E} field as if q is concentrated at $\vec{r}=0$

$$|z| < R. \quad \frac{z-R}{|z-R|} = -1, \quad \frac{z+R}{|z+R|} = 1 \quad \vec{r}=0$$

$$\vec{E}_p = 0$$

Field lines and Gauss's law

Using integrations to find \vec{E} field, as

shown in the above, is generally quite involved mathematically and may not be

easily done. Therefore, it would be

desired to have more friendly methods

to compute \vec{E} .

For this purpose, it is found that plotting

out $\vec{E}(\vec{r})$ would be useful.

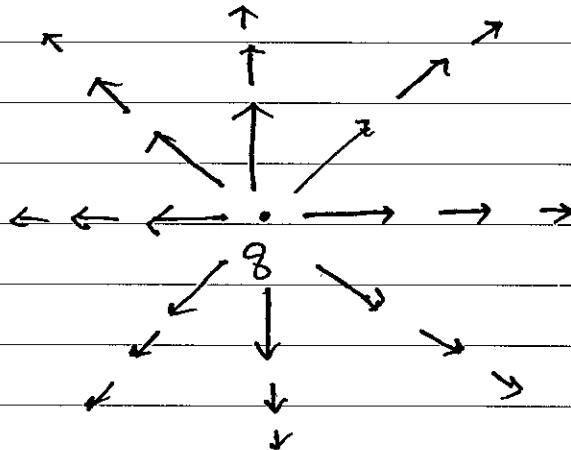
Consider the \vec{E} field due to a charge q

at $\vec{r}=0$,

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$$

At each point, one can draw an arrow

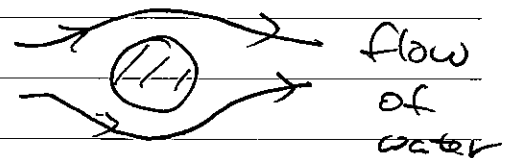
in proportional to \vec{E} , and obtains



Clearly, one sees that similar to flow

of water, these arrows represent some kind

of flow.



To mimic the flow of water,

it is useful to connect all arrows

to make it continuous.

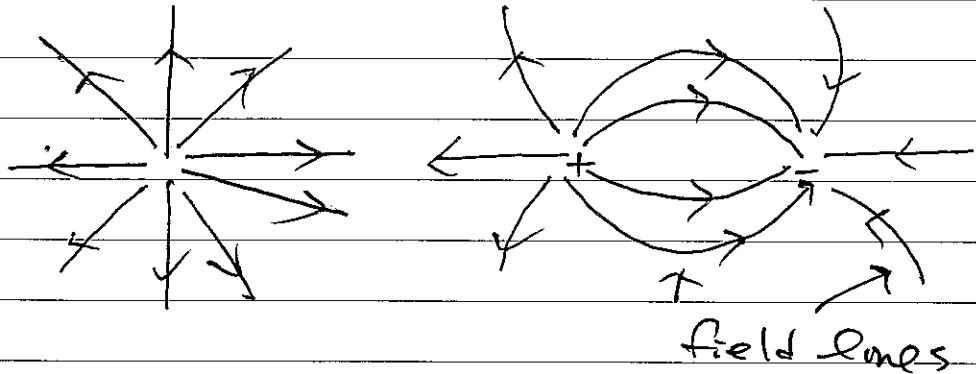
However, ^{in order} to represent ^{be able to}

the strength of \vec{E} , in the place with some \vec{E}

the density of lines increases and is

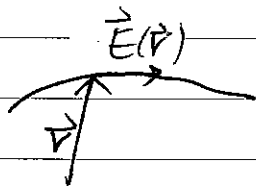
in proportional to $|\vec{E}|$. Therefore, one

gets



Formally, the curve of each field line is

determined by $d\vec{r} \parallel \vec{E}(\vec{r})$



i.e. $\frac{dx}{E_x} = \frac{dy}{E_y} = \frac{dz}{E_z} \quad \text{--- } \textcircled{D}$

which can be used to solve the equation for each curve.

One sees that field lines start from positive charges and end at negative charges.

Field lines don't intersect with other as

at each point, there is only one direction

of $\vec{E}(\vec{r})$!

To characterize density of field lines, it's useful to define the flux of \vec{E} .

through a surface S by

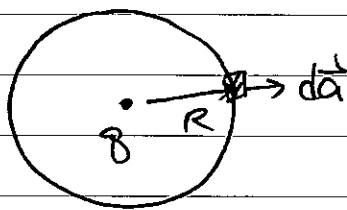
$$\Phi_E \equiv \int_S \vec{E} \cdot d\vec{a} \dots \textcircled{9}$$

which measures number of field lines that pass through S .

The flow picture apparently suggests that if one computes the ^{total} flux of a closed surface surrounding the charge, it measures the total charge inside the surface. — essence of the Gauss's law.

Take a point charge as an example, if the surface is a spherical surface of radius R ,

one gets the total flux

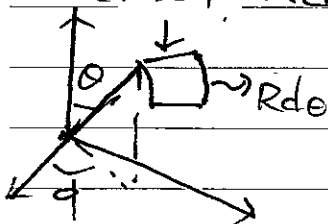


or

$$\Phi_E = \frac{1}{4\pi\epsilon_0} \oint \frac{q}{R^2} \hat{R} \cdot d\vec{a}$$

Solid
angle

$$R^2 \sin\theta d\theta d\phi \therefore d\vec{a} = R^2 \sin\theta d\theta d\phi \hat{R}, \quad \sin\theta d\theta d\phi \equiv d\Omega$$



$$\therefore \hat{R} \cdot d\vec{a} = R^2 \sin\theta d\theta d\phi$$

$$\Phi_E = \frac{q}{4\pi\epsilon_0} \underbrace{\int_0^\pi d\theta \int_0^{2\pi} d\phi \sin\theta}_{4\pi \text{ (area of unit sphere)}} = \frac{q}{\epsilon_0}$$

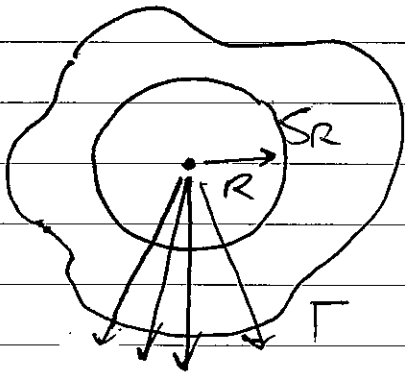
$$\therefore \oint_{S_R} \vec{E} \cdot d\vec{a} = q/\epsilon_0 \quad \dots (10)$$

which is independent of R

S_R = spherical surface of radius R
centered at q

Now, Eq. (10) is also valid for any other surfaces that enclose q because for any

surfaces Γ , one can find a spherical surface that is either enclosed by Γ or encloses Γ .



From the flow picture, it's clear that what leaves S_R also enters Γ .

There is no sink/source between S_R & Γ .

$$\therefore \oint_{\Gamma} \vec{E} \cdot d\vec{a} = \oint_{S_R} \vec{E} \cdot d\vec{a}$$

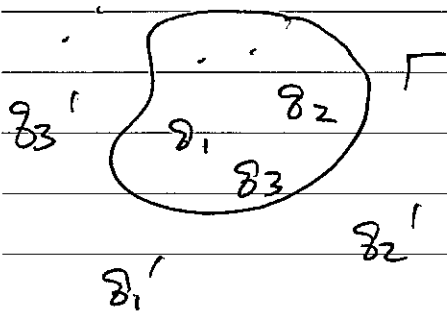
Using eq. (10), one obtains

$$\oint_{\Gamma} \vec{E} \cdot d\vec{a} = q/\epsilon_0 \quad \dots (11)$$

for any Γ that encloses q !

Eq. (1) can be easily generalized to the case with many charges. Suppose Γ encloses

q_1, q_2, q_3, \dots . By the principle of



superposition, the electric field \vec{E} on

Γ is the summation of

\vec{E}_i from q_i (inside) and \vec{E}_i' from

q_i' (outside).

$$\vec{E} = (\vec{E}_1 + \vec{E}_2 + \dots + \vec{E}_n + \dots) + (\vec{E}_1' + \vec{E}_2' + \dots + \vec{E}_n' + \dots)$$

$$\therefore \oint_{\Gamma} \vec{E} \cdot d\vec{a} = \sum_i \oint_{\Gamma} \vec{E}_i \cdot d\vec{a} + \sum_i \oint_{\Gamma} \vec{E}_i' \cdot d\vec{a}$$

$$\therefore \oint_{\Gamma} \vec{E}_i' \cdot d\vec{a} = 0$$

$$\oint_{\Gamma} \vec{E}_i \cdot d\vec{a} = \frac{q_i}{\epsilon_0}$$

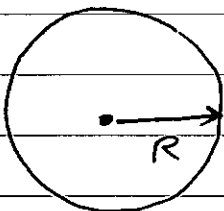
$$\therefore \oint_{\Gamma} \vec{E} \cdot d\vec{a} = \frac{1}{\epsilon_0} \sum_i q_i = \frac{1}{\epsilon_0} Q_{\text{enclosed}} \quad (12)$$

Eq. (12) is the integral form of the Gauss's law.

Application of Gauss's Law.

The Gauss's law ^{when combined with symmetries of space} is equivalent to the Coulomb law.

For instance, for a given point charge q at $\vec{r}=0$, the isotropy of space implies that the electric field \vec{E}



S_R

must align with \hat{R} , and depends only on R .

Therefore, from the Gauss's

law $\oint_{S_R} \vec{E} \cdot d\vec{a} = \frac{q}{\epsilon_0}$ and $\vec{E} = E(R) \hat{R}$,

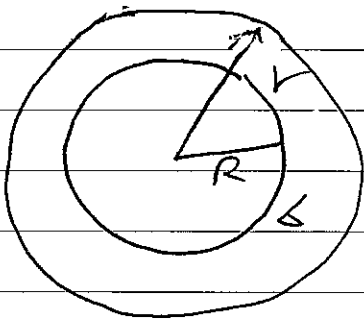
$$\begin{aligned} \text{one gets } \oint_{S_R} \vec{E} \cdot d\vec{a} &= \oint_{S_R} E(R) R^2 \sin\theta d\theta d\phi \\ &= R^2 E(R) \cdot 4\pi = \frac{q}{\epsilon_0} \end{aligned}$$

$$\therefore E(R) = \frac{1}{4\pi\epsilon_0} \frac{q}{R^2}, \quad \vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{R^2} \hat{R}$$

one recovers the Coulomb law.

Similarly, using the Gauss's law, one can ^{easily} find the problem of E field due to a

Uniformly charged spherical surface:



for $r > R$, one
 consider a concentric
 spherical surface of
 radius r .

Again, the electric field at \vec{r} must
 be parallel to \vec{r} , $\vec{E} = E(r)\hat{r}$.

Since $\oint_{\mathcal{S}_r} \vec{E} \cdot d\vec{a} = \oint_{\mathcal{S}_r} E(r) \cdot r^2 \sin\theta d\theta d\phi$

$$= r^2 E(r) \cdot 4\pi = \frac{1}{\epsilon_0} Q_{\text{enclosed}}$$

$$= \frac{1}{\epsilon_0} \times \underbrace{4\pi R^2 \sigma}_{Q}$$

$$\therefore E(r) = \frac{Q}{\epsilon_0} \frac{1}{r^2} = \frac{1}{4\pi\epsilon_0} \frac{Q}{r^2}$$

while for $r < R$, $\therefore Q_{\text{enclosed}} \Rightarrow$

$$\therefore E(r) = 0$$

One recovers previous results by direct
 integration.

As we can see, if the problem, for

Evaluating \vec{E} field has symmetries, one

Can use the Gauss's law to compute \vec{E} and the calculation can be greatly reduced effort

There are three kinds of symmetry that work.

(i) Spherical symmetry (Gauss surface = concentric sphere)

(ii) Cylindrical symmetry (Gauss surface = coaxial cylinder)

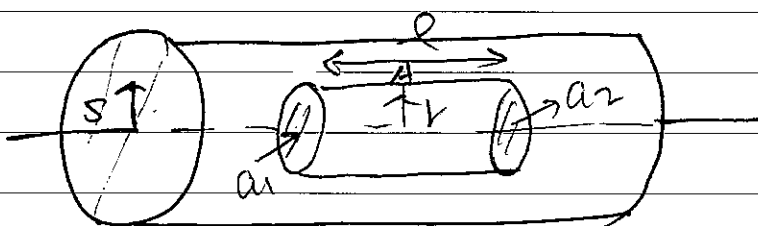
Example

A long cylinder carries a charge

density $\rho = ks$, $s =$ distance from

the axis, $k =$ some constant.

Find the electric field inside this cylinder.



For a point A deep inside the cylinder, the

electric field is

along the direction of \hat{r} .

This is true as long as A is far from two ends of the cylinder.

$$\therefore \vec{E} = E(r) \hat{r}$$

Consider a closed cylindrical surface shown in the figure. According to

the Gauss's law, one has

$$\oint \vec{E} \cdot d\vec{a} = \frac{1}{\epsilon_0} Q_{\text{enclosed}}$$

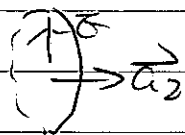
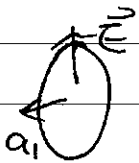
$$Q_{\text{enclosed}} = \int \rho dz$$

$$= \int K s' \cdot s' ds' d\phi dz$$

$$= 2\pi r K \int_0^r s'^2 ds'$$

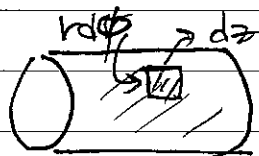
$$= \frac{2\pi r K}{3} r^3$$

On the other hand, $\because \int_{\vec{a}_1} \vec{E} \cdot d\vec{a} = 0 \quad \vec{E} \perp \vec{a}_1$



$\int_{\vec{a}_2} \vec{E} \cdot d\vec{a} = 0 \quad \vec{E} \perp \vec{a}_2$

for lateral surface



$$\int \vec{E} \cdot d\vec{a} = \int E(r) \cdot r d\phi dz = E(r) \cdot 2\pi r L$$

$$\therefore 2\pi r E(r) Q = \frac{1}{\epsilon_0} Q_{\text{enclosed}}$$

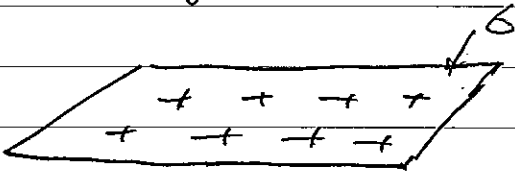
$$= \frac{1}{\epsilon_0} \frac{2\pi r K}{3} V^3$$

$$\therefore E(r) = \frac{1}{3\epsilon_0} K V^2$$

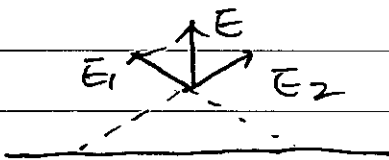
$$\therefore \vec{E} = \frac{1}{3\epsilon_0} K V^2 \hat{r}$$

(iii) Plane symmetry (Use pill box as the Gauss's surface)

Example: Find the electric field of an infinite plane with a uniform surface charge density σ

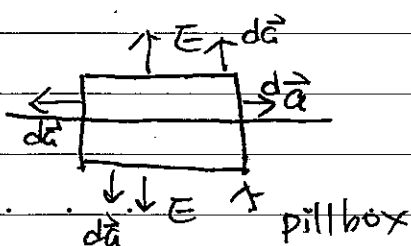


Sol. First, from consideration of symmetries,

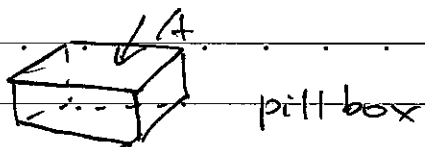


the electric field E must be perpendicular to the

plane. Therefore, one considers



a closed surface shown in the left figure: a pillbox



If the area of top and bottom surfaces for the pill box is A , then

$$\oint_{\text{pillbox}} \vec{E} \cdot d\vec{a} = 2EA$$

The lateral surfaces do n't contribute as $\vec{E} \perp d\vec{a}$ for these surfaces.

$$\therefore \oint_{\text{pillbox}} \vec{E} \cdot d\vec{a} = \frac{1}{\epsilon_0} Q_{\text{enclosed}} = \frac{1}{\epsilon_0} A\sigma$$

$$\therefore 2EA = \frac{1}{\epsilon_0} A\sigma, \quad E = \frac{\sigma}{2\epsilon_0}$$

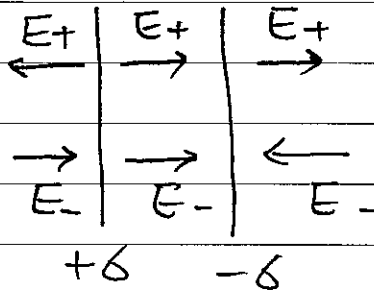
In general, even though the usage of the Gauss's law is restricted to cases with symmetries, using the principle of superpositions, one can evaluate systems with combined objects \vec{E} of different symmetries.

example. two infinite parallel planes carry equal but opposite uniform charge density $\pm\sigma$. Find \vec{E} in all space points.

For $+\sigma$ plane, one has: $E_+ = \frac{\sigma}{2\epsilon_0}$ pointing

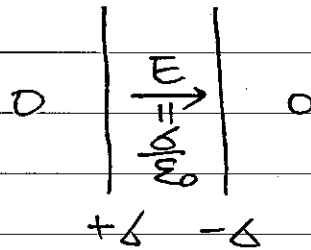
outwards, while for $-\sigma$ plane, $E = E_- = \frac{\sigma}{2\epsilon_0}$

point inwards, as follows



Using the principle of superposition, $E = E_+ + E_-$,

one obtains

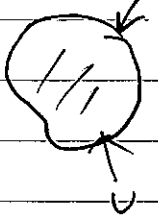


Differential form of the Gauss's law

From the integral form of the Gauss's law,

one has

$$\oint_{\partial V} \vec{E} \cdot d\vec{a} = \frac{1}{\epsilon_0} Q_{\text{enclosed}}$$



On the other hand, if $\rho = \rho(\vec{r})$ is the

charge density at \vec{r} , $Q_{\text{enclosed}} = \int_V \rho(\vec{r}) d\tau$. (13)

From the divergence theorem, one has

$$\oint_{\partial V} \vec{E} \cdot d\vec{a} = \int_V \vec{\nabla} \cdot \vec{E} \, d\tau \quad \dots (14)$$

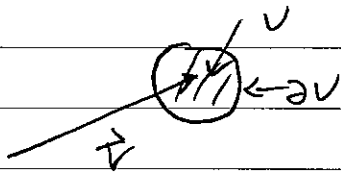
Combining eqs. (3) and (14), we obtain

$$\int_V \vec{\nabla} \cdot \vec{E} \, d\tau = \int_V \frac{1}{\epsilon_0} \rho(\vec{r}) \, d\tau.$$

L. (15)

Eq. (15) is valid for any V . If we choose

V surrounding \vec{r} and take $V \rightarrow 0$, one gets



$$\vec{\nabla} \cdot \vec{E} \cdot V = \frac{1}{\epsilon_0} \rho(\vec{r}) V$$

i.e.
$$\vec{\nabla} \cdot \vec{E} = \frac{1}{\epsilon_0} \rho(\vec{r}) \quad \dots (16)$$

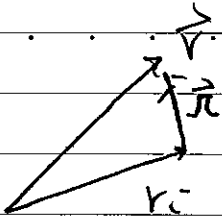
This is the Gauss's law in differential form.

Divergence of E

As we discussed, for a point charge q

located at \vec{r}_i , the charge density is

$$\rho(\vec{r}) = q_i \delta(\vec{r} - \vec{r}_i) \quad \dots (17)$$



Since the electric field due to q_i at P is

$$\begin{aligned}\vec{E} &= \frac{1}{4\pi\epsilon_0} \frac{q_i}{|\vec{P}-\vec{r}_i|^3} (\vec{P}-\vec{r}_i) \\ &= \frac{q_i}{4\pi\epsilon_0} \frac{\hat{r}}{r^2} \quad \dots (18)\end{aligned}$$

Combining eqs. (17), (18) and (16), one obtains

$$\frac{q_i}{4\pi\epsilon_0} \vec{\nabla} \cdot \frac{\hat{r}}{r^2} = \frac{q_i}{\epsilon_0} \delta(\vec{r})$$

Therefore, $\vec{\nabla} \cdot \frac{\hat{r}}{r^2} = 4\pi \delta(\vec{r}) \quad \dots (19)$

where $\delta(\vec{r}) = \delta^3(\vec{r}-\vec{r}_i)$ and we shall omit "3" and understand it means 3D

Dirac delta function, acting on \vec{r} !

More precisely, $\vec{\nabla} \cdot \frac{(\vec{P}-\vec{r}_i)}{4\pi|\vec{P}-\vec{r}_i|^3} = \delta(\vec{P}-\vec{r}_i) \quad \dots (20)$

The function $\frac{1}{4\pi} \frac{\vec{P}-\vec{r}_i}{|\vec{P}-\vec{r}_i|^3}$ that determines the electric field due to a unit charge is known as

the Green's function. $G(\vec{r}, \vec{r}_0) = \frac{\vec{r}-\vec{r}_0}{4\pi|\vec{r}-\vec{r}_0|^3}$

which can be also viewed as a description of how \vec{E} field propagates from \vec{r}_c to \vec{r} from a unit charge.

Due to the principle of superposition, once G is known, one knows $\vec{E}(\vec{r})$ from the knowledge of charge density:

Eq. (7)

$$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\vec{r}-\vec{r}'}{|\vec{r}-\vec{r}'|^3} \rho(\vec{r}') dz'$$

$$= \int G(\vec{r}, \vec{r}') \frac{\rho(\vec{r}')}{\epsilon_0} dz' \quad \dots (21)$$

It's easy to check that \vec{E} in eq. (21) is indeed a solution to eq. (6):

$$\vec{\nabla} \cdot \vec{E} = \int [\vec{\nabla} \cdot G(\vec{r}, \vec{r}')] \frac{\rho(\vec{r}')}{\epsilon_0} dz'$$

$$= \int \delta(\vec{r}-\vec{r}') \frac{\rho(\vec{r}')}{\epsilon_0} dz' = \frac{1}{\epsilon_0} \rho(\vec{r}).$$

Eq. (21) states the total E field ^{at \vec{r}} is summation of contributions from all charges at \vec{r}' . The propagation of \vec{E} from charges to \vec{r} is G which does not depend on charge density only.

depends on positions \vec{r} and \vec{r}' .

The response (\vec{E}) at \vec{r} is linear in

charge density. This feature is generally

true for all linear systems.

Example: Direct check $\vec{\nabla} \cdot \frac{\vec{j}}{r^2} = 4\pi \delta(\vec{r})$.

$$\vec{j} \neq 0 \quad \vec{\nabla} \cdot \frac{\vec{j}}{r^2} = 0$$

$$\text{Take } \vec{r}' = 0 \quad \therefore \vec{\nabla} \cdot \frac{\vec{r}}{r^3} = 0$$

$$\vec{\nabla} \cdot \frac{\vec{r}}{r^3} = \frac{\partial}{\partial x} \left(\frac{x}{r^3} \right) + \frac{\partial}{\partial y} \left(\frac{y}{r^3} \right) + \frac{\partial}{\partial z} \left(\frac{z}{r^3} \right)$$

$$\frac{\partial}{\partial x} \left(\frac{x}{r^3} \right) = \frac{\partial x}{\partial x} \frac{1}{r^3} + x \frac{\partial \frac{1}{r^3}}{\partial x}$$

$$= \frac{1}{r^3} - x \cdot \frac{3/2}{r^5} \frac{\partial x^2}{\partial x} = \frac{1}{r^3} - \frac{3x^2}{r^5}$$

$$\therefore \vec{\nabla} \cdot \frac{\vec{r}}{r^3} = \frac{3}{r^3} - \frac{3}{r^5} (x^2 + y^2 + z^2) = 0 \quad \text{if } r \neq 0$$

(One can also calculate it using spherical coordinates)

This derivation is not valid for $r=0$

as $\frac{\vec{r}}{r^3}$ is not defined at $r=0$.

For $r=0$, one needs to replace $\frac{\vec{r}}{r^3}$ by

a sequence of functions that approach $\frac{\vec{r}}{r^3}$.

We consider $\frac{\vec{r}}{r^3} \rightarrow \frac{\vec{r}}{(r^2+a^2)^{3/2}}$ and take $a \rightarrow 0$

at the end.

$$\vec{\nabla} \cdot \frac{\vec{F}}{(r^2+a^2)^{3/2}} = \frac{\partial x}{\partial x} \frac{1}{(r^2+a^2)^{3/2}} + \frac{\partial y}{\partial y} \frac{1}{(r^2+a^2)^{3/2}} + \frac{\partial z}{\partial z} \frac{1}{(r^2+a^2)^{3/2}}$$

$$+ x \frac{\partial}{\partial x} \left(\frac{1}{(r^2+a^2)^{3/2}} \right) + \dots$$

$$= \frac{3}{(r^2+a^2)^{3/2}} - \left[x \frac{3}{2} \frac{1}{(r^2+a^2)^{5/2}} \frac{\partial r^2}{\partial x} + y \frac{3}{2} \frac{1}{(r^2+a^2)^{5/2}} \frac{\partial r^2}{\partial y} + z \frac{3}{2} \frac{1}{(r^2+a^2)^{5/2}} \frac{\partial r^2}{\partial z} \right]$$

$$= \frac{3}{(r^2+a^2)^{3/2}} - \frac{3r^2}{(r^2+a^2)^{5/2}} = \frac{3a^2}{(r^2+a^2)^{5/2}} = f(r)$$

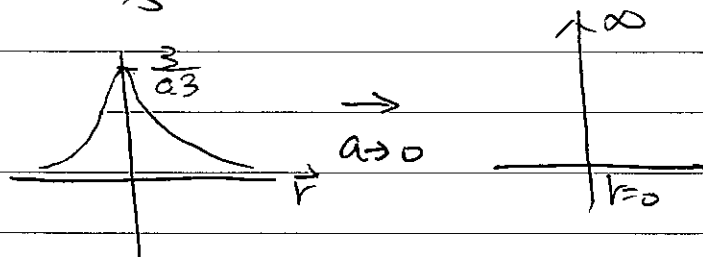
(One can also use the spherical coordinate to calculate it: $\vec{\nabla} \cdot \vec{v} = \frac{1}{r^2} \frac{d}{dr} (r^2 v_r)$)

$$\therefore \int d\tau \frac{3a^2}{(r^2+a^2)^{5/2}} = 4\pi \int_0^\infty r^2 dr \frac{3a^2}{(r^2+a^2)^{5/2}}$$

$$= 12\pi \int_0^\infty \frac{x^2 dx}{(x^2+1)^{5/2}} = 4\pi$$

\uparrow $x = r/a$ $\underbrace{\hspace{2cm}}_{1/3}$

and $f(r) \rightarrow$

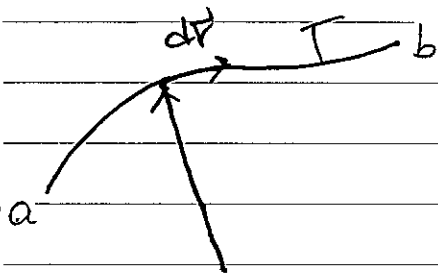


$$\lim_{a \rightarrow 0} f(r) = 4\pi \delta(\vec{r}) \quad \therefore \vec{\nabla} \cdot \frac{\vec{F}}{r^3} = 4\pi \delta(\vec{r})$$

$\nabla \times \vec{E}$ and path dependence of work

One of important quantity for the force is the work done by the force,

When the force is a vector field, the work done is generally path dependent.



As shown in the left figure, if one applies a force on a charged particle q to counter the electric force $q\vec{E}$ and

moves q from a to b , the work that needs to be done is \int_a^b along Γ

$$W = \int_a^b \vec{F} \cdot d\vec{r} = -q \int_a^b \vec{E} \cdot d\vec{r} \quad \text{--- (22)}$$

From elementary consideration on conservation of energy, the work must be due to either (i) change of kinetic energy or (ii) change of configuration.

Since the change of kinetic energy is zero, the work done is attributed to the change.

of configuration (as particle is moved from a to b).

This is how the "potential energy" is

introduced as one argues that the work done goes to ^{change of} the potential energy U .

$$W = U_b - U_a \quad (23)$$

However, the potential energy U is only

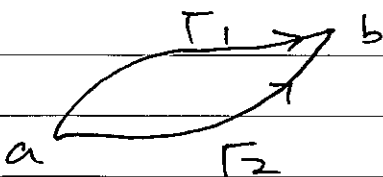
a function of position. Hence this can

be achieved only when W is path independent.

Note that U is proportional to the charge q

and hence $U \equiv qV$. V is the potential. (24)

The path independence implies



$$\int_a^b \vec{E} \cdot d\vec{e} = \int_a^b \vec{E} \cdot d\vec{e} \quad (25)$$

Γ_1 Γ_2

(Such force is termed conservative)

The question is how to judge eq. (25).

First, if eq. (25) is correct, the integral is

independent of Γ and can only depend on

end points a and b , \therefore For fixed a ,

$$\therefore \int_a^b \vec{E} \cdot d\vec{\ell} \text{ path-independent}$$

$$\Rightarrow \int_a^b \vec{E} \cdot d\vec{\ell} = \text{a function of } b$$

$$\text{Let } \int_a^b \vec{E} \cdot d\vec{\ell} = f(\vec{r}_b)$$

$$\therefore \int_a^{b+db} \vec{E} \cdot d\vec{\ell} = f(\vec{r}_b + d\vec{r}_b)$$

$$f(\vec{r}_b + d\vec{r}_b) - f(\vec{r}_b) = \int_{\vec{r}_b}^{\vec{r}_b + d\vec{r}_b} \vec{E} \cdot d\vec{\ell}$$

$$\text{taking } d\vec{r}_b \rightarrow 0, \therefore \int_{\vec{r}_b}^{\vec{r}_b + d\vec{r}_b} \vec{E} \cdot d\vec{\ell} = \vec{E}(\vec{r}_b) \cdot d\vec{r}_b$$

$$f(\vec{r}_b + d\vec{r}_b) - f(\vec{r}_b) = \nabla f(\vec{r}_b) \cdot d\vec{r}_b$$

$$\therefore \nabla f(\vec{r}_b) \cdot d\vec{r}_b = \vec{E}(\vec{r}_b) \cdot d\vec{r}_b$$

$$\therefore \vec{E} = \nabla f, \text{ in fact, } f = -V$$

$$\therefore \int_a^b \vec{E} \cdot d\vec{\ell} \Rightarrow \vec{E} = -\nabla V \quad \dots (26)$$

Path-independency

i.e. $\vec{E} = \text{gradient of } (-\text{potential})$

So that $\vec{E} \cdot d\vec{\ell} = -\nabla V \cdot d\vec{\ell} = -dV$ is

a total differential

$\dots (27)$
work done by

Therefore, to check whether a force is

path independent, one can check whether the force

Can be written as a gradient: $\vec{F} = -\nabla U$
 or $\vec{E} = -\nabla V$

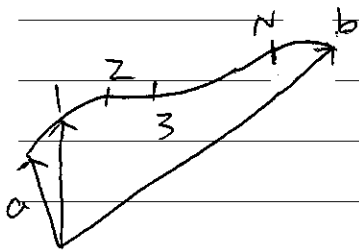
Note that conversely, if $\vec{E} = -\nabla V$

$$\vec{E} \cdot d\vec{r} = -\nabla V \cdot d\vec{r} = -dV \quad (=V(\vec{r}+d\vec{r}) - V(\vec{r}))$$

$$\therefore \int_a^b \vec{E} \cdot d\vec{r} = -\int_a^b dV$$

$$= -(V_a - V_1 + V_2 - V_1 + V_3 - V_2 + \dots + V_b - V_{N-1})$$

$$= V_b - V_a \quad \text{is path independent}$$



$$\therefore \vec{E} = -\nabla U \Leftrightarrow \int_a^b \vec{E} \cdot d\vec{r}$$

path-independent

L. (28)

Generally, however, it is difficult to check

if $\vec{E} = -\nabla V$, therefore, one needs other more convenient criteria.

For this purpose, one first realizes that if

$\int_a^b \vec{E} \cdot d\vec{r}$ is path-independent, eq. (28) is satisfied.

Furthermore, since $\int_a^b \vec{E} \cdot d\vec{r} = -\int_b^a \vec{E} \cdot d\vec{r}$ for any Γ
 ($b > a$, $d\vec{r} \rightarrow -d\vec{r}$).

eg. (25) is equivalently as

$$\int_{\Gamma_1}^b \vec{E} \cdot d\vec{e} = \int_a^b \vec{E} \cdot d\vec{e} = - \int_b^a \vec{E} \cdot d\vec{e}$$

$$\therefore \left(\int_{\Gamma_2}^b + \int_{\Gamma_1}^a \right) \vec{E} \cdot d\vec{e} = 0$$

$$\text{i.e., } \oint_{\Gamma_1 + \Gamma_2} \vec{E} \cdot d\vec{e} = 0$$

Therefore, if $\int_{\Gamma} \vec{E} \cdot d\vec{e}$ is path-independent

for any $\Gamma \Rightarrow \oint_C \vec{E} \cdot d\vec{e} = 0$ for any closed curve C .

Conversely, if $\oint_C \vec{E} \cdot d\vec{e} = 0$ for any closed,

$\int_a^b \vec{E} \cdot d\vec{e}$ is path-independent,

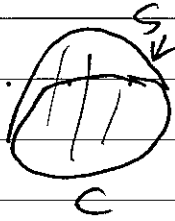
$\therefore \int_{\Gamma} \vec{E} \cdot d\vec{e}$ path-independent for any Γ

$\Leftrightarrow \oint_C \vec{E} \cdot d\vec{e} = 0$ for any closed curve C

L... (29)

Now, according to the Stoke's theorem,

$$\oint_C \vec{E} \cdot d\vec{e} = \oint_S \nabla \times \vec{E} \cdot d\vec{s}$$



By taking $S \rightarrow 0$, one gets

$$\vec{S} \cdot \vec{\nabla} \times \vec{E} = 0$$

$$\therefore \vec{\nabla} \times \vec{E} = 0$$

Conversely, if $\vec{\nabla} \times \vec{E} = 0$, one has

$$\oint_C \vec{E} \cdot d\vec{\ell} = 0 \text{ for any } C.$$

$$\therefore \vec{\nabla} \times \vec{E} = 0 \Leftrightarrow \oint_C \vec{E} \cdot d\vec{\ell} = 0 \quad \dots (30)$$

Combining eqs. (28), (29) and (30), one obtains

that in a region R (Simply-connected, see below), the followings are equivalent:

$\int_a^b \int_{\Gamma} \vec{E} \cdot d\vec{\ell} = \text{path-independent} \Leftrightarrow \vec{E} = -\nabla V \text{ in } R$ $\Leftrightarrow \oint_C \vec{E} \cdot d\vec{\ell} = 0 \text{ for any } C \in R \Leftrightarrow \vec{\nabla} \times \vec{E} = 0 \text{ in } R \quad \dots (31)$
--

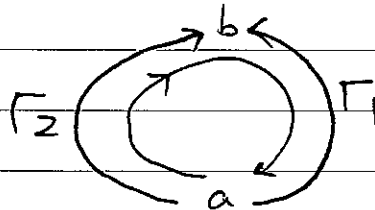
Physical picture: There is a physical picture behind eq. (31): $\vec{\nabla} \times \vec{E}$ measures "vortex" flow

in \vec{E} . When $\vec{\nabla} \times \vec{E} \neq 0$, there is a

vortex flow. which is the reason why

different paths need different work.

as some paths are against flow, the other paths are not as shown in below:



Γ_1 is against flow $\therefore \int_{\Gamma_1} \neq \int_{\Gamma_2}$!

Therefore, if there is ^{no} vortex, works along different paths are the same.

Note that the statement

$$\nabla \times \vec{E} = 0 \Leftrightarrow \int_a^b \vec{E} \cdot d\vec{e} \text{ is path-independent}$$

is only valid when the region R that $\nabla \times \vec{E} = 0$ is simply-connected, i.e., there is no hole in R !

In general, when the region R has a hole, i.e., not simply-connected, $\nabla \times \vec{E} = 0$ in R

does not imply $\int_a^b \vec{E} \cdot d\vec{e}$ is path-independent!

A good example is to consider the case

when there is a hole, it could happen

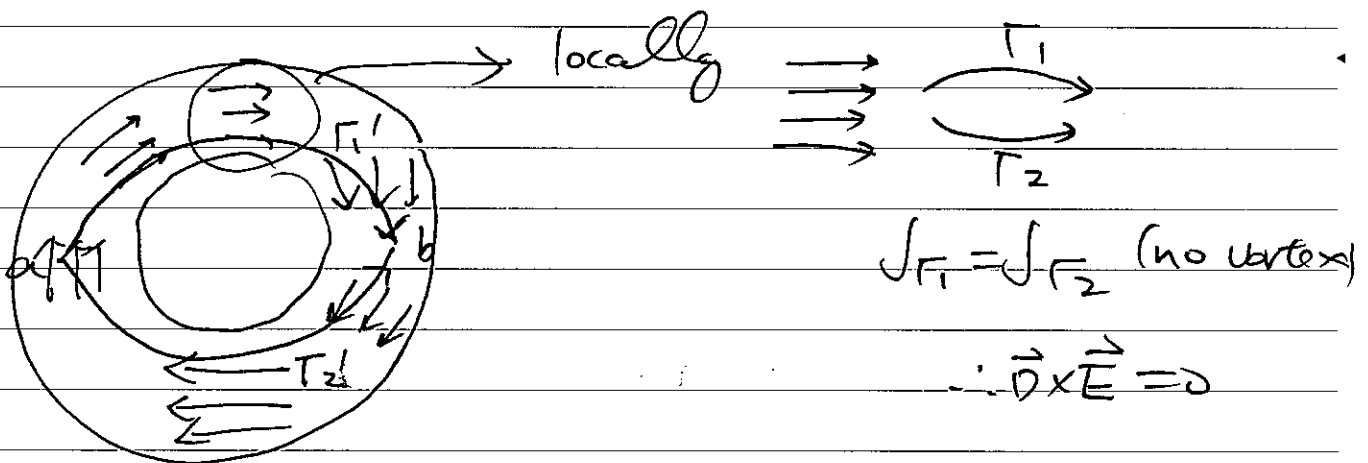
that locally $\int \vec{E} \cdot d\vec{\ell}$ is path-independent

$$\text{so that } \oint_{\partial S} \vec{E} \cdot d\vec{\ell} = \int_S \nabla \times \vec{E} \cdot d\vec{a} = 0$$

$$\therefore \nabla \times \vec{E} = 0$$

$$\text{but globally, } \int_{\Gamma_1}^b \vec{E} \cdot d\vec{\ell} \neq \int_{\Gamma_2}^b \vec{E} \cdot d\vec{\ell}$$

See below:

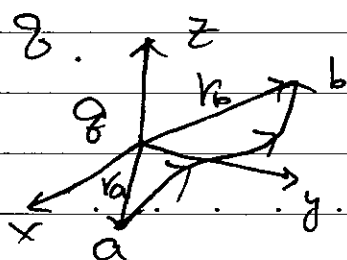


$\nabla \times \vec{E}$ for static charges

Due to the principle of superposition, one only needs to consider \vec{E} due to a point

charge q .

at 0



$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$$

to calculate $\int_a^b \vec{E} \cdot d\vec{\ell}$, one notes

$$\text{that } d\vec{\ell} = dr \hat{r} + r d\theta \hat{\theta} + r \sin\theta d\phi \hat{\phi}$$

$$\therefore \vec{E} \cdot d\vec{\ell} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} dr$$

$$\therefore \int_a^b \vec{E} \cdot d\vec{\ell} = \frac{q}{4\pi\epsilon_0} \int_{r_a}^{r_b} \frac{dr}{r^2}$$

$$= \frac{-q}{4\pi\epsilon_0} \frac{1}{r} \Big|_{r_a}^{r_b} = \frac{1}{4\pi\epsilon_0} \left(\frac{q}{r_a} - \frac{q}{r_b} \right)$$

$$\equiv -(V_b - V_a)$$

$$\therefore V(r) = \frac{q}{4\pi\epsilon_0 r} + \text{const}$$

Usually, by defining $V(r=\infty) = 0$, one

can remove the constant and gets

$$V(r) = \frac{1}{4\pi\epsilon_0} \frac{q}{r} \quad \text{--- (32)}$$

$$\text{check } -\nabla V = -\left(\frac{\partial}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial}{\partial \theta} \hat{\theta} + \frac{1}{r \sin\theta} \frac{\partial}{\partial \phi} \hat{\phi} \right) V(r)$$

$$= -\frac{q}{4\pi\epsilon_0} \frac{\partial}{\partial r} \left(\frac{1}{r} \right) \hat{r} = \frac{q}{4\pi\epsilon_0} \frac{\hat{r}}{r^2} = \vec{E}$$

$$\therefore \vec{E} = -\nabla V$$

The path independence of work implies

$$\vec{\nabla} \times \vec{E} = 0 \text{ which can be checked}$$

directly: $\vec{E} = E_r \hat{r}$ using spherical coordinate

$$\begin{aligned} \vec{\nabla} \times \vec{E} &= \frac{1}{r \sin \theta} \left(\frac{\partial}{\partial \theta} (\sin \theta E_\phi) - \frac{\partial E_\theta}{\partial \phi} \right) \hat{r} \\ &+ \frac{1}{r} \left[\frac{1}{\sin \theta} \frac{\partial E_r}{\partial \phi} - \frac{\partial}{\partial r} (r E_\phi) \right] \hat{\theta} \\ &+ \frac{1}{r} \left[\frac{\partial}{\partial r} (r E_\theta) - \frac{\partial E_r}{\partial \theta} \right] \hat{\phi} = 0 \end{aligned}$$

Electric potential

As we have shown, for static charges,

$$\vec{\nabla} \times \vec{E} = 0, \quad \vec{E} = -\nabla V$$

V is the electric potential.

Its unit is Newton/charge = Newton/Coulomb.

\equiv volt.

V has no absolute value as one can

add $V + \text{any constant} = V'$, V & V' will

yield the same \vec{E} .

Usually, one needs a reference point to fix the constant.

Physically, the absolute value of V has no meaning. Only the difference of V has physical meaning.

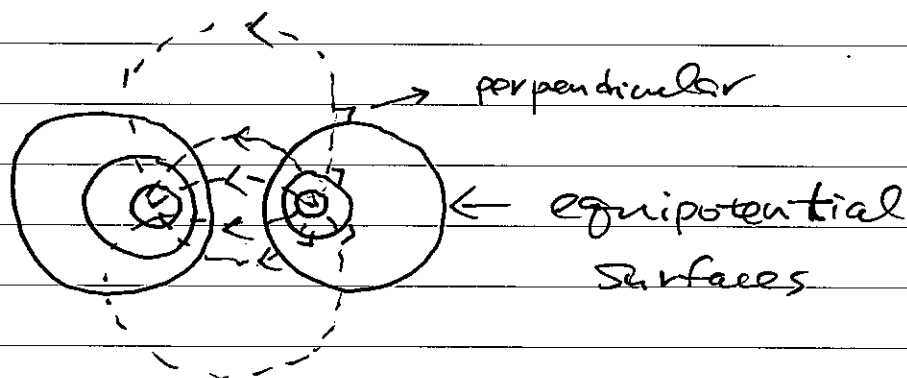
Field lines and equipotential surfaces

The relation $\vec{E} = -\nabla V$ implies

that $\vec{E} \perp$ constant surfaces of V .

This results from general properties of gradient, ∇ .

Since field lines are lines with tangential vectors parallel to \vec{E} , therefore, field lines are perpendicular to equipotential surfaces.



Superposition Principle

Since \vec{E} obeys the superposition principle

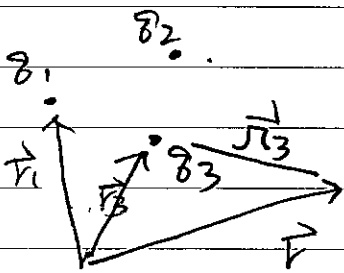
$$\vec{E} = \vec{E}_1 + \vec{E}_2 + \dots$$

the potential $\vec{E} = -\nabla V$ also obeys the superposition principle

$$V = V_1 + V_2 + V_3 + \dots$$

i.e., the potential at \vec{r} = summation due to all charges. Hence eq. (32) can

be generalized to



$$V(r) = \frac{1}{4\pi\epsilon_0} \left(\frac{q_1}{r_1} + \frac{q_2}{r_2} + \dots \right)$$

$$= \frac{1}{4\pi\epsilon_0} \sum_i \frac{q_i}{r_i} \quad \dots (33)$$

For the continuous distribution,

$$V(r) = \frac{1}{4\pi\epsilon_0} \int \frac{dq'}{|\vec{r} - \vec{r}'|}$$

$$dq' = \rho(r') dz'$$

$$\therefore V(r) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(r') dz'}{|\vec{r} - \vec{r}'|} \quad \dots (34)$$

The electric field due to ρ is

$\vec{E} = -\nabla V$ which is given by eq (7)

$$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{1}{|\vec{r}-\vec{r}'|^3} (\vec{r}-\vec{r}') \rho(\vec{r}') d\tau'$$

The advantage of eq (34) is that it is

an integral over a scalar function,

while one needs to consider 3-component

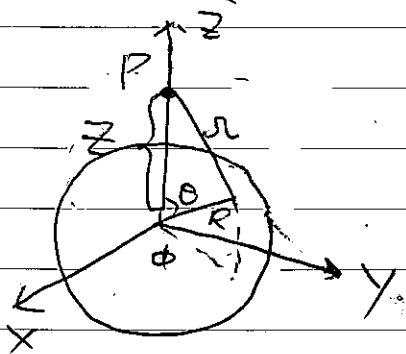
integration in eq (7). The integration

effort is often reduced.

Example: Find the potential of

a uniformly charged spherical shell of

radius R



an area element at (θ, ϕ)

$$= R^2 \sin\theta d\theta d\phi$$

\therefore if $\delta =$ charge density

$$V_P = \int \frac{\delta R^2 \sin\theta d\theta d\phi}{4\pi\epsilon_0 R}$$

$\therefore R^2 = R^2 + z^2 - 2Rz\cos\theta$ independent of ϕ

$$\therefore \int d\phi = 2\pi$$

$$U_p = \frac{\delta R^2}{4\pi\epsilon_0} \times 2\pi \int_0^\pi \frac{\sin\theta d\theta}{\sqrt{R^2 + z^2 - 2Rz\cos\theta}}$$

$$= \frac{\delta R^2}{2\epsilon_0} \int_{-1}^1 \frac{d\cos\theta}{\sqrt{R^2 + z^2 - 2Rz\cos\theta}}$$

$$= \frac{\delta R^2}{2\epsilon_0} \left. \frac{1}{Rz} \sqrt{R^2 + z^2 - 2Rz\cos\theta} \right|_0^\pi$$

$$= \frac{\delta R^2}{2\epsilon_0} \frac{1}{z} \left[\sqrt{(R+z)^2} - \sqrt{(R-z)^2} \right]$$

$$z > R \left\{ = \frac{\delta R}{2\epsilon_0} \frac{1}{z} (R+z + (R-z)) = \frac{R^2 \delta}{\epsilon_0 z} \right.$$

$$z < R \left\{ = \frac{\delta R}{2\epsilon_0} \frac{1}{z} (R+z + z-R) = \frac{R\delta}{2\epsilon_0}$$

If we set $q = 4\pi R^2 \delta = \text{total charge}$,

$$\text{one has } U(r) = \frac{1}{4\pi\epsilon_0} \frac{q}{r} \quad r \geq R$$

$$= \frac{1}{4\pi\epsilon_0} \frac{q}{R} \quad r \leq R$$

is consistent with the electric field calculation we did before.

Poisson's equation and Laplace's equation

— the "differential form" for V .

As we have shown, the \vec{E} field

for static charges obeys:

$$\left. \begin{aligned} \vec{\nabla} \times \vec{E} &= 0 \\ \vec{\nabla} \cdot \vec{E} &= \frac{\rho}{\epsilon_0} \end{aligned} \right\} \textcircled{35}$$

According to the Helmholtz theorem, the above two uniquely determines \vec{E} in a region.

Mathematically, to solve \vec{E} , one starts

from $\vec{\nabla} \times \vec{E} = 0$ and concludes $\vec{E} = -\nabla V$.

Substituting $\vec{E} = -\nabla V$ into $\vec{\nabla} \cdot \vec{E} = \rho/\epsilon_0$, one gets

$$\nabla^2 V = -\rho/\epsilon_0 \quad \dots \textcircled{36}$$

which is known as the Poisson's equation.

When $\rho = 0$, one gets

$$\nabla^2 V = 0 \quad \dots \textcircled{37}$$

which is the Laplace equation, which will be discussed later.

Eq. $\textcircled{36}$ is the differential form of eq. $\textcircled{34}$.

Solving the differential equation is often easier than performing the integration.

However, solutions to eq. (36) are only for the voltage whose absolute values have no meaning. That is, if V is a solution,

$V + \text{constant}$ is a solution. To fix the constant, one often employ the boundary

condition. Eq. (36) is thus solved with the boundary conditions.

For infinite systems, we often take the boundary condition as

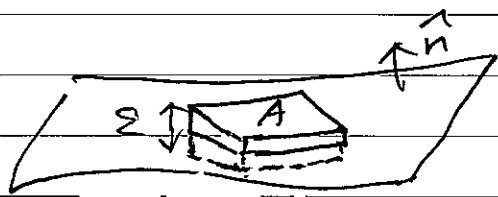
$$V(r) \rightarrow 0 \quad \text{as} \quad r \rightarrow \infty \quad \dots \quad (37)$$

In general, the region of V that we are interested is finite. One needs different boundary conditions as

will be discussed in below.

Boundary conditions

One of the situations for the boundary conditions is that one knows the surface charge density on a surface and needs to know how the electric field and potential change across the surface.



As shown in the left figure, we take a small pillbox

as the Gaussian surface.

The width of the pill box $\epsilon \rightarrow 0$, hence side surfaces don't contribute

\therefore If A is small enough, one gets

$$\vec{E} \cdot \vec{A} |_{\text{above}} + \vec{E} \cdot \vec{A} |_{\text{below}} = \frac{1}{\epsilon_0} \sigma A$$

$$\therefore \vec{A} |_{\text{above}} = A \hat{n}, \quad \vec{A} |_{\text{below}} = -A \hat{n}$$

\therefore The above eq. becomes $E_{\text{above}}^{\perp} - E_{\text{below}}^{\perp} = \frac{\sigma}{\epsilon_0}$ (39)

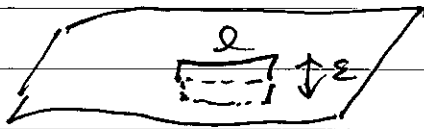
Eq. (39) states that the normal component of \vec{E} across a surface is discontinuous if there is a surface charge.

On the other hand, for electrostatic field,

$$\nabla \times \vec{E} = 0 \text{ is always true.}$$

$$\therefore \oint \vec{E} \cdot d\vec{l} = 0 \text{ for any closed surface.}$$

Consider a small rectangular loop shown in the below.



For $\epsilon \rightarrow 0$, side edges have no contribution.

$$\therefore \oint \vec{E} \cdot d\vec{l} = \vec{E} \cdot \vec{l} |_{\text{above}} + \vec{E} \cdot \vec{l} |_{\text{below}} = 0$$

$$\vec{l} |_{\text{above}} = -\vec{l} |_{\text{below}} \therefore E^{\parallel}_{\text{above}} = E^{\parallel}_{\text{below}} \quad (40)$$

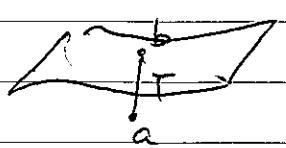
\parallel indicates components in parallel to the surface.

Combining eqs. (39) & (40), one gets $\vec{E}_{\text{above}} - \vec{E}_{\text{below}} = \frac{\sigma}{\epsilon_0} \hat{n}$

$$\text{--- (BC) --- (41)}$$

Eq. (41) is the boundary condition for \vec{E} . One needs to convert it into BC for the potential.

For the potential, $\therefore V_{\text{above}} - V_{\text{below}} = -\int_a^b \vec{E} \cdot d\vec{l}$



$$\text{taking } \vec{l}_{ab} \rightarrow 0, \int_a^b \vec{E} \cdot d\vec{l} \rightarrow 0$$

$$\therefore V_{\text{above}} = V_{\text{below}} \quad \text{--- (42)}$$

\therefore The potential is continuous across the surface. However, derivative of V is not.

Together with $\vec{E} = -\nabla V$, eq. (41) becomes

$$\left. \begin{aligned} \nabla U_{\text{above}} - \nabla U_{\text{below}} &= -\frac{\sigma}{\epsilon_0} \hat{n} \\ \text{or } \frac{dU_{\text{above}}}{dn} - \frac{dU_{\text{below}}}{dn} &= -\frac{\sigma}{\epsilon_0} \end{aligned} \right\} \text{--- (43)}$$

coordinate along \hat{n} direction

i.e. $\frac{dU}{dn} = \hat{n} \cdot \nabla U =$ normal derivative of U

Eqs (42) & (43) are boundary conditions of the potential across surface charges.

Work and energy in electrostatics

Work

As we have seen, ^{if one} moves a charge q from a to b , ^{in the presence of an} \vec{E} field, one needs to counter

the electric force and performs the work

$$W = \int_a^b \vec{F} \cdot d\vec{s} = \int_a^b (-q\vec{E}) \cdot d\vec{s} = q(V(b) - V(a))$$

--- (44)

In particular, if we take the charge

from ∞ to \vec{r} , the work needs to

be done \therefore

$$W = q (V(r) - V(\infty))$$

Setting $V(\infty) = 0$ (reference) point, we

get
$$W = q V(r) = \text{potential energy} \quad \text{--- (45)}$$

Energy of a charge distribution

Using eq. (45) (taking $V = \infty$, $V = 0$ as

the reference point), one can deduce

the work that needs to be done

to assemble a distribution of charges.

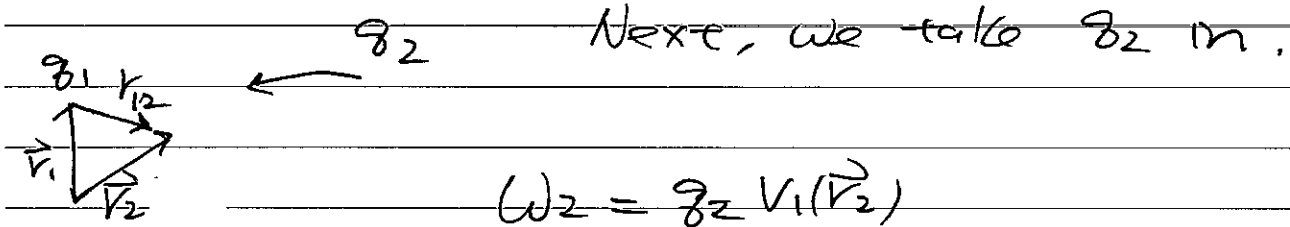
For point charges, to assemble q_1, q_2, q_3

... at $\vec{r}_1, \vec{r}_2, \vec{r}_3, \dots$, one first

bring in q_1 to \vec{r}_1 , this takes no

work as the space has no other

Charges $\therefore W_1 = 0$



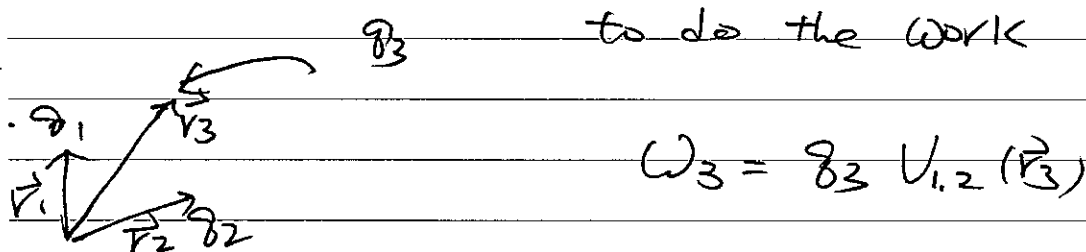
$$W_2 = q_2 V_1(\vec{r}_2)$$

$$V_1(\vec{r}_2) = \frac{1}{4\pi\epsilon_0} \frac{q_1}{r_{12}}$$

$$r_{ij} = |\vec{r}_i - \vec{r}_j|$$

$$\therefore W_2 = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r_{12}}$$

Now, if we bring in q_3 , we need



$$W_3 = q_3 V_{1,2}(\vec{r}_3)$$

Using the principle of superposition,

$$V_{1,2}(\vec{r}_3) = V_1(\vec{r}_3) + V_2(\vec{r}_3)$$

$$= \frac{1}{4\pi\epsilon_0} \frac{q_1}{r_{13}} + \frac{1}{4\pi\epsilon_0} \frac{q_2}{r_{23}}$$

$$\therefore W_3 = \frac{1}{4\pi\epsilon_0} \left(\frac{q_1 q_3}{r_{13}} + \frac{q_2 q_3}{r_{23}} \right)$$

Similarly, the work to bring q_4 in is

$$W_4 = \frac{1}{4\pi\epsilon_0} q_4 \left(\frac{q_1}{r_{14}} + \frac{q_2}{r_{24}} + \frac{q_3}{r_{34}} \right)$$

and the work to bring in q_n is

$$W_n = \frac{1}{4\pi\epsilon_0} q_n \left(\frac{q_1}{r_{1n}} + \frac{q_2}{r_{2n}} + \dots + \frac{q_{n-1}}{r_{(n-1)n}} \right)$$

\therefore Total work

$$W = W_1 + W_2 + W_3 + \dots + W_n$$

$$= \frac{1}{4\pi\epsilon_0} \sum_{\text{each pair } (i,j)}$$

$$= \frac{1}{4\pi\epsilon_0} \sum_{i=1}^n \sum_{\substack{j=i+1 \\ (j>i)}}^n \frac{q_i q_j}{r_{ij}}$$

$j > i$ is used to avoid double-counting of (i,j) pair.

One can also include $j < i$, but due to double-counting of each (i,j) pair ((i,j) or (j,i)),

we need to divide it by 2:

$$W = \frac{1}{2} \frac{1}{4\pi\epsilon_0} \sum_{i=1}^n \sum_{j \neq i}^n \frac{q_i q_j}{r_{ij}} = \frac{1}{8\pi\epsilon_0} \sum_{i \neq j} \frac{q_i q_j}{r_{ij}}$$

$$= \frac{1}{2} \sum_{i=1}^n q_i \left(\underbrace{\sum_{j \neq i}^n \frac{1}{4\pi\epsilon_0 r_{ij}}}_{\text{total potential of all other charges at } r_i} \right) \dots \textcircled{46}$$

total potential of all other charges at r_i

$$= \frac{1}{2} \sum_{i=1}^n q_i V(r_i) \quad \dots (47)$$

$V(r_i)$ is the potential at r_i (excluding the potential due to q_i at r_i !)

Eq. (47) is the total work to assemble

q_1, q_2, \dots, q_n at $\vec{r}_1, \vec{r}_2, \dots, \vec{r}_n$.

Note that this work does not include

the work that ^{needs} to assemble each q_i itself!

For a continuous charge distribution, clearly,

one replace q_i by $\rho(\vec{r}) d\tau$

$$\therefore W = \frac{1}{2} \int \rho(\vec{r}) V(\vec{r}) d\tau \quad \dots (48)$$

Now, using $\rho/\epsilon_0 = \vec{\nabla} \cdot \vec{E}$, one gets

(Note that in principle

$$W = \frac{\epsilon_0}{2} \int (\vec{\nabla} \cdot \vec{E}) V d\tau$$

V excludes the contribution of $\rho d\tau$ at \vec{r} , however

$\because d\tau \rightarrow 0$, the contribution $\rightarrow 0$;

Using integration by parts, one has

$$(\vec{\nabla} \cdot \vec{E}) V = \vec{\nabla} \cdot (\vec{E} V) - \vec{E} \cdot (\vec{\nabla} V) = \vec{\nabla} \cdot (\vec{E} V) + E^2$$

$$\therefore W = \frac{\epsilon_0}{2} \int E^2 d\tau + \frac{\epsilon_0}{2} \int \vec{\nabla} \cdot (\vec{E}U) d\tau$$

From the divergence theorem,

$$\int_V \vec{\nabla} \cdot (\vec{E}U) d\tau = \oint_{\partial V} U \vec{E} \cdot d\vec{a}$$

taking $V \rightarrow \infty$, $\partial V \rightarrow \infty$, $\therefore U \rightarrow \frac{1}{r}$, $\vec{E} \rightarrow \frac{1}{r^2}$

$$\therefore \oint_{\partial V} U \vec{E} \cdot d\vec{a} \rightarrow 0 \quad (\text{as } d\vec{a} \rightarrow r^2)$$

One obtains

$$W = \frac{\epsilon_0}{2} \int E^2 d\tau \quad \dots \textcircled{49}$$

work is stored in field with
i.e. energy density per volume in the

$$\text{space} = \frac{1}{2} \epsilon_0 E^2 \quad \dots \textcircled{50}$$

Note that when q_i is replaced by q_j in eq. (49)

in eq. (49), eq. (49) ^{also} includes work that

needs to assemble q_i itself! (self-energy)

(as $V(r)$ is the full potential used in (49)!) ^{also}

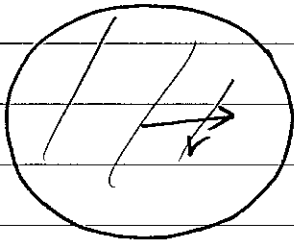
That is why eq. (50) is always positive

while eq. (49) may become negative.

Example: Find the energy of a

uniformly charged sphere with

total charge Q and radius R .



Using Gauss's law,

E at r satisfies

$$E \cdot 4\pi r^2 = \frac{1}{\epsilon_0} Q_{\text{enclosed}}$$

$$= \frac{1}{\epsilon_0} \left(\frac{4\pi}{3} r^3 \right) \cdot \rho$$

$$\therefore E = \frac{\rho}{3\epsilon_0} r \quad \text{for } 0 \leq r \leq R$$

$$\text{For } r > R, \quad E = \frac{1}{4\pi\epsilon_0} \frac{Q}{r^2} \quad \left(\rho = \frac{Q}{\frac{4\pi}{3} R^3} \right)$$

For the potential, one has

$$V = \frac{1}{4\pi\epsilon_0} \frac{Q}{r} \quad r \geq R$$

$$V = -\int^r E dr = -\frac{\rho}{6\epsilon_0} r^2 + \text{const} \quad 0 \leq r \leq R$$

$$= \frac{-Q}{8\pi\epsilon_0 R^3} r^2 + C$$

$\therefore V$ has to be continuous at $r=R$,

$$\therefore \frac{1}{4\pi\epsilon_0} \frac{Q}{R} = \frac{-Q}{8\pi\epsilon_0 R^3} R^2 + C$$

$$\therefore C = \frac{+3}{8\pi G} \frac{g}{R}$$

$$\therefore V = \frac{-g}{8\pi G R^2} r^2 + \frac{3}{8\pi G} \frac{g}{R} \quad \text{for } 0 \leq r \leq R$$

$$\therefore W = \frac{1}{2} \int \rho V dz$$

$$= \frac{\rho}{2} \int_0^R 4\pi r^2 dr \left(\frac{-g}{8\pi G R^2} r^2 + \frac{3}{8\pi G} \frac{g}{R} \right)$$

$$= \frac{\rho}{2} \cdot \frac{3g}{8\pi G} \frac{1}{R} \cdot \frac{4\pi}{3} R^3$$

$$+ \frac{\rho(-g)}{2 \cdot 8\pi G R^2} \cdot 4\pi \int_0^R r^4 dr$$

$$= \frac{1}{8\pi G R} \frac{3g^2}{2} - \frac{\rho g}{2 \cdot 8\pi G R^2} 4\pi \frac{R^5}{5}$$

$$\frac{11}{5}$$

$$\frac{3}{5} \frac{g^2}{16\pi G R}$$

$$= \frac{3}{5} \frac{g^2}{4\pi G R}$$

One can also use eq. (4) to calculate

and find the same result.

Clearly, as $R \rightarrow 0$, $W \rightarrow \infty$. Therefore,

the classical point $= \infty$.

self-energy of

The divergence of self-energy can be

directly revealed by considering the \vec{E}

field of a point charge q

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$$

$$\therefore W = \frac{\epsilon_0}{2} \int E^2 d\tau$$

$$= \frac{\epsilon_0}{2} \left(\frac{q}{4\pi\epsilon_0}\right)^2 \int \frac{1}{r^4} r^2 \sin\theta d\theta d\phi dr$$

$$= \frac{\epsilon_0}{2} \left(\frac{q}{4\pi\epsilon_0}\right)^2 \cdot 4\pi \int_0^\infty \frac{dr}{r^2} = \infty$$

The infinite ^{energy} of a point charge is a recurring source of difficulty in E&M theory and

has plagued ^{physicists} in theory of E&M, ^{even quantum}

We shall discuss it later in this course.

Note that because W depends on E quadratically, it does not obey a superposition principle:

$$\text{if } \vec{E} = \vec{E}_1 + \vec{E}_2$$

$$W_{\text{total}} = \frac{\epsilon_0}{2} \int E^2 d\tau = \frac{\epsilon_0}{2} \int (\vec{E}_1 + \vec{E}_2)^2 d\tau$$

$$= \frac{\epsilon_0}{2} \int (E_1^2 + E_2^2 + 2\vec{E}_1 \cdot \vec{E}_2) d\tau = W_1 + W_2 + \epsilon_0 \int \vec{E}_1 \cdot \vec{E}_2 d\tau$$

$$\neq W_1 + W_2$$

Electric properties of conductors

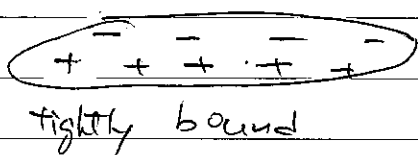
Insulator, conductor and perfect conductor

Materials are often classified according to their transport properties which we shall discuss later, are the abilities to carry currents.

They are insulators, conductors & semi-conductors

The ability to carry currents depends

on the availability of electrons



that are not bound to atoms and can move freely. (called free electrons)

For insulators, there is no free electron

and all electrons can not move in long distance and are attached to atoms.

On the other hand, in a conductor, which is often metallic, there are one or more electrons per atom that can move freely.

When there are unlimited free charges,

those are perfect conductors.

Perfect conductors are idealized conductors.

In real materials, there is no perfect conductor but metals are close for most purposes.

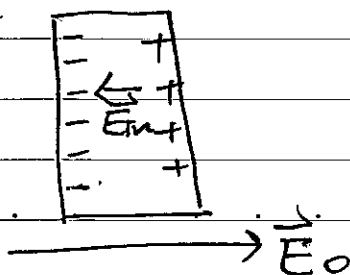
We shall assume conductors in this course are perfect.

Basic ^{electrostatic} properties of ideal conductors (perfect)

(i) $\vec{E} = 0$ inside.

If there is any field $\vec{E} \neq 0$, due to the unlimited free charges, those free charges will move and become current. This would not be electrostatic any more.

More precisely, for a given ideal conductor shown in below, in the presence \vec{E}_0 charges



of external will move in response

to \vec{E}_0 . However, due

to the boundary of the

Conductor, charges will accumulate at

surfaces of conductors

These surface charges, in turn, give

rise to an internal field \vec{E}_m to

cancel \vec{E}_0 ! $\vec{E} = \vec{E}_0 + \vec{E}_m \Rightarrow$

The process occurs in very short of time, practically instantaneous!

Note that the above is true only

when there are unlimited free charges.

For conductors with finite charges, the

cancellation of \vec{E} will not be complete

if \vec{E} is too strong!

(ii) $\rho = 0$ inside

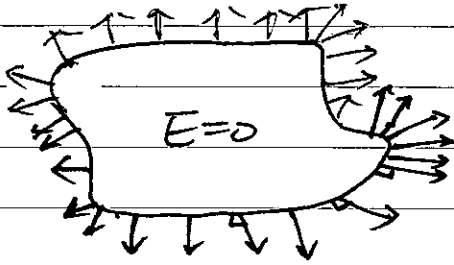
From (i), $\therefore \vec{E} = 0$, from $\vec{\nabla} \cdot \vec{E} = \rho / \epsilon_0$

$\therefore \rho = 0$

(iii) Any net charge resides on the surface. (consequence of (ii))

(iv) A conductor is an equipotential.

$\therefore \vec{E} = 0$ \therefore for any two points a & b



inside a conductor

the difference of their potential

$$V_a - V_b = - \int_b^a \vec{E} \cdot d\vec{e} \Rightarrow$$

$$\therefore V_b = V_a$$

Hence inside the conductor, $V = \text{const}$.

Outside the conductor, $\vec{E} \neq 0$

but $\therefore \vec{E} \perp$ equipotential surface,

$\therefore \vec{E} \perp$ surface of a conductor.

Induced charges & force on a conductor

As explained in the above, in the presence of external \vec{E}_0 , charges on a conductor can only reside on surfaces.

As a result, there are surface

charges characterized by surface charge density σ (C/m²) on a conductor.

$$\begin{array}{c} \delta \uparrow \vec{E} \\ + + + + \\ \vec{E} = 0 \\ \text{Conductor} \end{array}$$

Since $\vec{E} = 0$ inside the conductor, according to the boundary condition we derived, the E field outside must

be

$$\vec{E} = \frac{\delta}{\epsilon_0} \hat{n} \quad \dots (51)$$

ie. $\delta = -\epsilon_0 \frac{\partial V}{\partial n}$ \hat{n} = unit normal vector

Eq. (51) is not sufficient to solve \vec{E}

or δ on a conductor. It, however, gives

\vec{E} once δ is known.

Physically, δ is related to the curvature of the surface. For a ^{conducting} sphere of radius

$$R, \text{ one has } E = \frac{1}{4\pi\epsilon_0} \frac{q}{R^2}$$



$$\therefore \delta = \frac{q}{4\pi R^2}$$

Therefore, ^{for a fixed q} δ increases, if R reduces

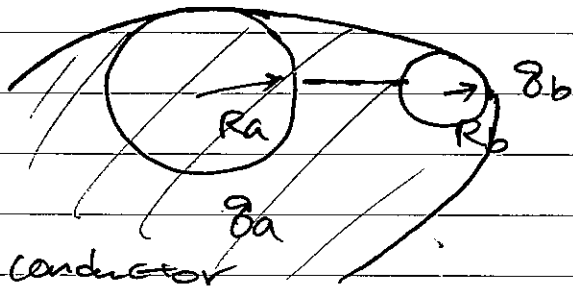
i.e. $R \downarrow$ (Curvature \uparrow), $E \uparrow$.

Since the surface of a conductor consists of parts

with different curvatures, ρ is not fixed, one considers the equilibrium between two spheres

with R_a, R_b : potentials

are the same



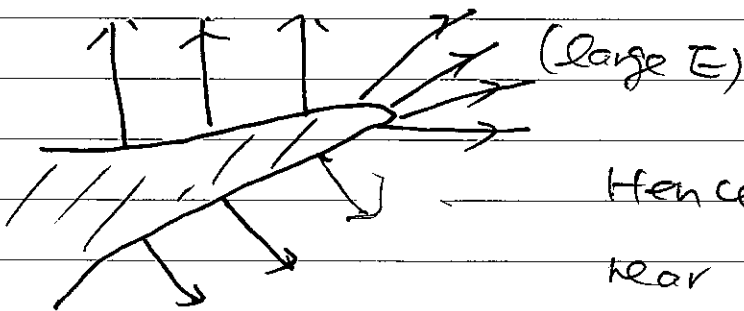
$$\frac{\rho_a}{4\pi\epsilon_0 R_a} = \frac{\rho_b}{4\pi\epsilon_0 R_b}$$

$$\therefore \frac{\rho_a}{\rho_b} = \frac{R_a}{R_b}$$

$$\therefore \frac{E_a}{E_b} = \frac{\rho_a / R_a^2}{\rho_b / R_b^2} = \frac{\rho_a}{\rho_b} \frac{R_b^2}{R_a^2} = \frac{R_b}{R_a}$$

Therefore, $E \propto \frac{1}{R}$ (= curvature)

$$\sigma \propto \frac{1}{R} \quad \dots \quad (1-2)$$



Hence density of E lines near a conductor is larger when the curvature is larger (see the left figure)

This is often summarized as the statement: the electric field near a sharp area of a conductor is enhanced!

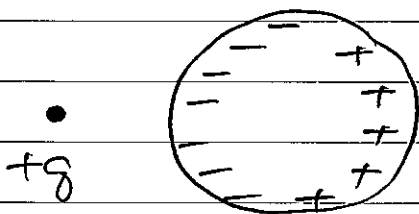
If the electric field is large enough so that air molecules are accelerated and collide with each other that leads to breakdown of air, it may lead to discharge phenomena. (尖端放电)

Induced charges

The integration of σ over ^{the} surface of the conductor gives the net charge induced on the conductor.

These are known as induced charges.

For instance, in the presence of a positive



charge, the induced charge

of a sphere near

+q is negative,

while the induced charge away from +q is positive.

As a result, the net induced charge

on the sphere is zero:

$$\oint \sigma da = 0$$

The net charge on a closed surface induced

is not necessary zero. For instance,

if there is a cavity inside the

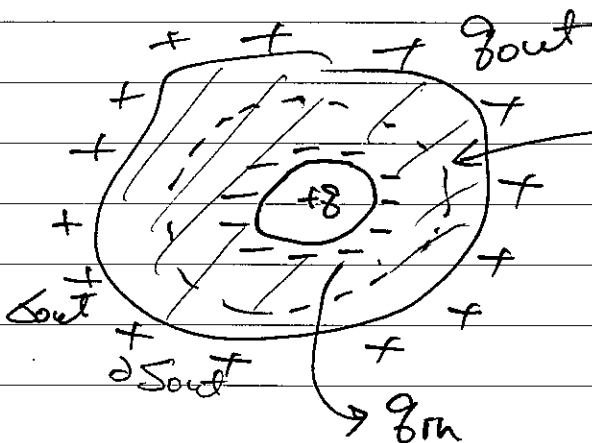
conductor as shown in below, the induced

inner surface $q_{in} \neq 0$:
charge on the

Consider a Gaussian

surface dS_m that

is buried inside
the conductor.



$$\therefore \vec{E} = 0 \text{ on } dS_m$$

$$\therefore \oint_{dS_m} \vec{E} \cdot d\vec{a} = 0 = \frac{1}{\epsilon_0} q_{total}$$

$$\therefore q_{total} = q + q_{in} = 0$$

$$q_{in} = -q$$

Note that if the conductor is

neutral before $+q$ is introduced,

we must have

$$q_{in} + q_{out} = 0$$

$$\therefore q_{out} = -q_{in} = +q !$$

Effect of shielding

As we have seen, when there is a

cavity in a neutral conductor, the net charge

on the outside surface is q .

With

(i) Charges inside cavity

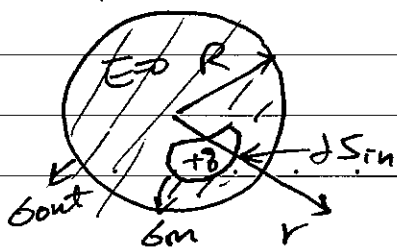
In fact, as we shall argue in below,

q_{out} is independent of the shape of

cavity and is solely determined by geometry

of outside surface.

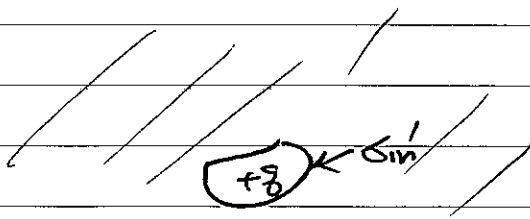
Example: \downarrow S_{out} = sphere of radius R



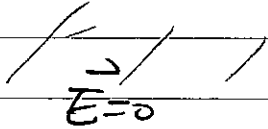
We shall argue that

$$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r} \quad \therefore (53) \quad \text{for } r > R$$

Consider a different case when $R \rightarrow \infty$.



Let S' be ^{the} surface charge in this case.



Clearly,

$$\vec{E}_q + \vec{E}_n = 0 \text{ for}$$

$\vec{r} \in \text{conductor}$

Now for the problem of finite R , we

shall set $S_n = S'_n$, therefore

$$\vec{E}_q + \vec{E}_n = 0 \text{ for all points}$$

(including $r > R$ region) outside the cavity.

Therefore, outside the cavity, \vec{E} is entirely determined by S_{out} .

From the above construction, one has

$$\vec{E}(\vec{r}) = \vec{E}_q(\vec{r}) + \vec{E}_{S_n}(\vec{r}) + \vec{E}_{S_{out}}(\vec{r})$$

which satisfies (i) $\vec{E} = 0$ inside conductor

(ii) $\vec{E} \rightarrow 0$, $r \rightarrow \infty$.

(iii) $\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}(\vec{r})$ inside the cavity.

Due to uniqueness of solutions for E field

as we shall prove later, the constructed

solution (via principle^{of} superposition) is

the solution!

Hence, \vec{E} is entirely determined

by \vec{E}_{out} , i.e., by σ_{out} .

For spherical shape that σ_{out} is distributed,

clearly, by symmetry, σ_{out} is a constant

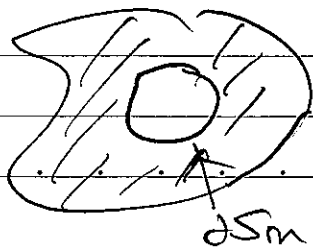
$$\therefore \sigma_{out} = \frac{q}{4\pi R^2}$$

$$\therefore \vec{E}_{out} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r} \quad \text{for } r > R$$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r} \quad \text{for } r > R$$

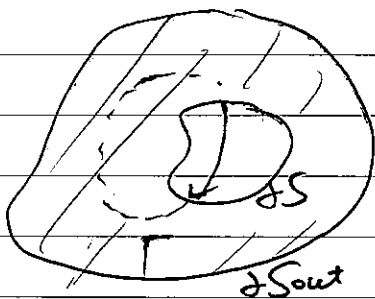
(ii) No charge inside cavity

When there is not any charge inside the cavity as shown in the left figure, there is



no charge on dS_{in} . \square

Clearly, if this is not true, there must be positive & negative charges on dS_{in} and the E field inside the cavity must start from some positive charge and end at some negative charge on dS_{in} as shown in below.



This is, however, not possible because one can form a closed curve

T , the integral $\oint \vec{E} \cdot d\vec{c} \neq 0$

which violates $\oint \vec{E} \cdot d\vec{c} = 0$ for electrostatics.

Hence one concludes that there is no charge on dS !

That is, no matter what is arranged on dS_{out} & outside, there is no charge on dS . The cavity appears to be protected against charges outside.


(electrostatics)

This is the effect of shielding: a

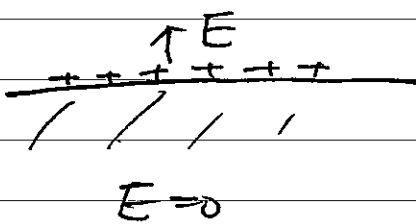
Conductor can shield electrostatic perturbations from penetrating ^{objects in} cavity inside the conductor.

The shielding effect is usually implemented using the Faraday cage made by metal.

In practice, the enclosure does not

have to be solid conductor, and chicken wire is suffice.  ← chicken wire as a net.

Force acting on a conductor



As we have seen, the E field on the surface of a conductor is given by

$$\vec{E} = \frac{\sigma}{\epsilon_0} \hat{n}$$

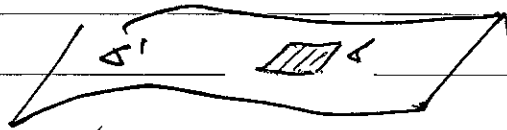
However, this field comes from two

Contributions: external field & field produced by σ . (Other than σ)

Only the external field yields a force on σ .

While the field produced by σ itself does not act on σ itself!

For this purpose, we consider a small parallelogram ^{on the surface} shown in the left figure.



Close to the parallelogram, the E field due to σ is $\pm \frac{\sigma}{2\epsilon_0}$ as shown.

out $\uparrow\uparrow\uparrow \frac{\sigma}{2\epsilon_0} = E_{up}$

$\downarrow\downarrow\downarrow \frac{\sigma}{2\epsilon_0} = E_{down}$

The total E is the sum

of $\pm \frac{\sigma}{2\epsilon_0}$ and E' due to other

surface charges σ' & external charges

$$\therefore \vec{E}_{down} + \vec{E}' = 0 \quad (\text{inside conductor})$$

$$\therefore \vec{E}' = \frac{\sigma}{2\epsilon_0} \hat{n} \quad \text{--- (54)}$$

$$\therefore \vec{E}_{out} = \vec{E}' + \vec{E}_{up} = \frac{\sigma}{2\epsilon_0} \hat{n} + \frac{\sigma}{2\epsilon_0} \hat{n} = \frac{\sigma}{\epsilon_0} \hat{n}$$

in agreement with $\vec{E} = \frac{\sigma}{\epsilon_0} \hat{n}$.

\uparrow
the solution

The force is due to E' .

Therefore, for a ^{small} area a around \vec{r} ,

the charge $q = a \sigma$
on a

\therefore the force that acts on a

$$= q \cdot \vec{E}' = \frac{\sigma^2}{2\epsilon_0} a \hat{n}$$

\therefore Force per area at \vec{r}

$$\vec{f} = \frac{1}{2\epsilon_0} \sigma^2(\vec{r}) \hat{n} \quad \text{--- (55)}$$

This is essentially the pressure ^(P) that acts on $\sigma(\vec{r})$.

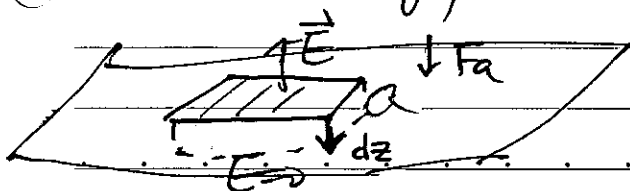
$$P = \frac{1}{2\epsilon_0} \sigma^2 = \frac{1}{2} \epsilon_0 E^2$$

$$E = \frac{\sigma}{\epsilon_0} \quad \text{--- (56)}$$

$\frac{1}{2} \epsilon_0 E^2$ is the energy density at \vec{r} .

Eq. (56) states that the ^{electrostatic} pressure at \vec{r}

= energy density.



This can be understood by imagining the area a moving

into the conductor. dz .

via the applied force F_a

$\therefore F_a$ has to counter P

$$\therefore F_a/a = P$$

The work done by $F_a = F_a dz$ — (5)

When a is moving down dz , the energy of the system increases by $\frac{\epsilon_0}{2} E^2 a dz$ — (6)

because before the movement, $E \Rightarrow$ in

adz , E is now non-vanishing in adz .

Hence the work must go to $\frac{\epsilon_0}{2} E^2 a dz$

Equating (5) & (6) yields

$$F_a = \frac{\epsilon_0}{2} E^2 a = aP$$

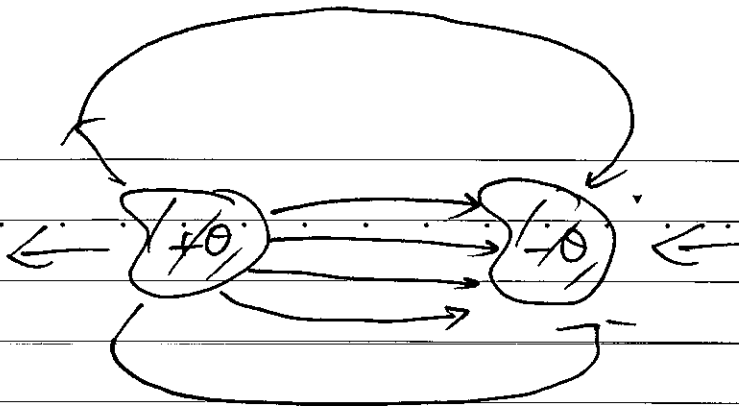
$$\therefore P = \frac{1}{2} \epsilon_0 E^2$$

Capacitors

A capacitor is a special arrangement

of two conductors with $+Q$ on one

and $-Q$ on the other as shown in below.



Clearly, the charges on two conductors

re-arrange: electric fields such

that more E lines are confined between

$\pm Q$ conductors.

\therefore Energy density $= \frac{1}{2} \epsilon_0 E^2$, one can

see that energy is now stored between

two conductors. \therefore The capacitor can be used to store electric energy.

The total energy stored $= \int \frac{1}{2} \epsilon_0 E^2 dz$

is the work done to separate $\pm Q$ charges.

To find the total work, one needs to

know the potential difference ^{dv} between two

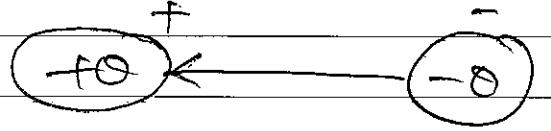
conductors so that moving dq from one

conductor to another is known

$$dW = dq \cdot dv \quad \dots \textcircled{59}$$

For a given charge Q , the potential

difference



$$V \equiv V_+ - V_- = - \int_-^+ \vec{E} \cdot d\vec{l} \quad \dots (60)$$

$$\text{Now, } \vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r}')}{|\vec{r} - \vec{r}'|^3} (\vec{r} - \vec{r}') d\tau'$$

From the principle of superposition, doubling Q doubles \vec{E} if ρ is doubled.

This is clearly a solution. From the

uniqueness of \vec{E} (electrostatic), one

concludes that $\vec{E} \propto Q$. $\dots (61)$

Hence eqs. (60) implies $V \propto Q$.

We write

$$\frac{Q}{V} \equiv C \quad \dots (62)$$

with C being defined as capacitance.

Clearly, C is a purely geometrical quantity

determined by sizes, shapes & separation

of two conductors. Its unit is Coulomb/

volt \equiv farads (F).

F is a large unit. In practice,

one uses microfarad ($10^{-6} F$) and

picofarad ($10^{-12} F$) more often.

In practice, sometimes, one discusses

the capacitance for a single conductor.

In that case, the second conductor

is set at $r = \infty$ with $V = 0$.

$\therefore C = Q/V$ Q & V are

charge and voltage of the conductor

--- (63)

This definition of capacitance is the

most general definition of capacitance.

In the case with many conductors with

Q_i, V_i for each conductor, one has

$(Q_1) V_1$ $(Q_2) V_2$

$(Q_3) V_3$

.....

$$Q_i = \sum_{j=1}^n C_{ij} V_j$$

with $C_{ii} \equiv$ capacitance

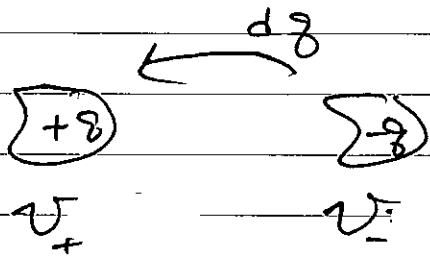
$C_{ij} (i \neq j) \equiv$ coefficients

of induction.

We shall stick to the case with

one or two conductors, and the definition of capacitance using eqs. (62) & (63).

To find the work for separating the charges into $\pm Q$, we start from an intermediate step when two conductors carry $\pm q$ charges.



To move dq from $-q$ to $+q$, one

needs to do the work

$$dW = V_+ dq + V_- (-dq)$$

$$= (V_+ - V_-) dq = \frac{Q}{C} dq$$

eq. (62)

$$\therefore W = \int dW = \int_0^Q \frac{Q}{C} dq = \frac{1}{2C} Q^2$$

$$= \frac{1}{2} CV^2 \quad \text{--- (63)}$$

$$Q = CV$$

with V being the final potential charged!

Note that eq (63) can be derived

by using eq (64) directly

$$W = \frac{1}{2} \int \rho V dz$$

$$= \frac{1}{2} \left(\int_+ \rho dz \right) V_+ + \frac{1}{2} \left(\int_- \rho dz \right) V_-$$

$$= \frac{1}{2} Q V_+ - \frac{1}{2} Q V_-$$

$$= \frac{1}{2} Q V = \frac{1}{2} C V^2$$

From the derivation, it is clearly the

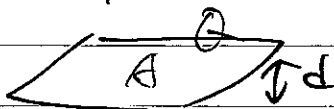
W includes not only the work separating

$+Q$ and $-Q$ but also the work between

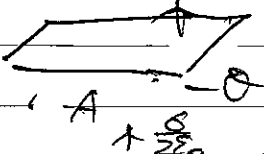
charges on Q ($-Q$) themselves.

$\therefore W$ includes self energy of $+Q$ & $-Q$.

Example: Parallel-plate capacitor



$$\sigma = Q/A$$



$$E = \frac{\sigma}{2\epsilon_0} + \frac{\sigma}{2\epsilon_0} = \frac{\sigma}{\epsilon_0}$$

$$U = Ed = \frac{\sigma}{\epsilon_0} d = \frac{Q}{A\epsilon_0} d = \frac{Q}{C}$$

$$\therefore C = \frac{A\epsilon_0}{d}$$

$$W = \frac{1}{2} C U^2 = \frac{1}{2} \frac{A\epsilon_0}{d} U^2$$

$$= \frac{1}{2} \frac{A\epsilon_0}{d} (Ed)^2$$

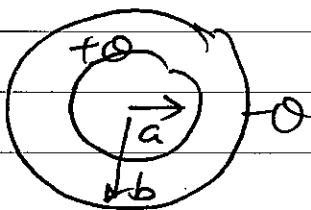
$$= \frac{1}{2} \epsilon_0 E^2 \cdot \underbrace{(Ad)}$$

volume between
two-plates

\therefore Clearly, both $\frac{1}{2} C U^2$ and $\int \frac{1}{2} \epsilon_0 E^2$

are the work for creating a capacitor
with voltage U .

Example: Capacitance of two concentric



spherical metal shells with
radii a and b ($b > a$)

$$\therefore \text{for } a < r < b, \quad \vec{E} = \frac{1}{4\pi\epsilon_0} \frac{Q}{r^2} \vec{r}$$

$$\therefore U = -\int_b^a \vec{E} \cdot d\vec{r} = -\frac{Q}{4\pi\epsilon_0} \int_b^a \frac{dr}{r^2}$$

$$= \frac{Q}{4\pi\epsilon_0} \frac{1}{r} \Big|_b^a = \frac{Q}{4\pi\epsilon_0} \left(\frac{1}{a} - \frac{1}{b} \right) = \frac{Q}{C}$$

$$\therefore C = 4\pi\epsilon_0 \frac{ab}{b-a}$$